Changes for the Better
Programmable Controllers
MELSEC-L series

## Little on size, Large on performance

The new $L$ series has a small footprint and is loaded with features.


# global impact of MITSUBISHI ELECTRIC 



Through Mitsubishi Electric's vision, "Changes for the Better" are possible for a brighter future.

## Changes for the Better

We bring together the best minds to create the best technologies. At Mitsubishi Electric, we understand that technology is the driving force of change in our lives. By bringing greater comfort to daily life, maximizing the efficiency of businesses and keeping things running across society, we integrate technology and innovation to bring changes for the better.

Mitsubishi Electric is involved in many areas including the following

## Energy and Electric Systems

A wide range of power and electrical products from generators to large-scale displays.

## Electronic Devices

A wide portfolio of cutting-edge semiconductor devices for systems and products.

## Home Appliance

Dependable consumer products like air conditioners and home entertainment systems.

## Information and Communication Systems

Commercial and consumer-centric equipment, products and systems.

## Industrial Automation Systems

Maximizing productivity and efficiency with cutting-edge automation technology.

## Simple

## Flexible

## Convenience that fits in the palm of your hand

The L Series is a compact-class controller, part of the MELSEC products renowned for exceptional cost verses performance and strong reliability. It provides the performance, functions, and capabilities required for today's demanding applications in a small package.
MELSEC-L Series greatly expands the range of functionality traditionally associated with compact programmable controllers and through user-centric design, pushes the limits of ease of use.

## Ideally configured to satisfy the applications requirements

MELSEC L Series has been designed with three key concepts in mind.

## Reliability

Robust and trusted MELSEC product quality.

## Ease-of-use

Enabling engineers and programmers to do their job as efficiently as possible to reduce costs.

## Flexibility

L Series is a cost-efficient control system flexible to
various applications, enabling an ideal system design.

Flexible I/O/
High-Speed Counter P. 48

Network
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[^0]

## Easy setup of built-in I/O functions

Configuring built-in I/O functions can be done easily by setting parameters using the programming tool.


Built-in I/O function example parameter settings Pulse Catch: 0.01 ms (response time) Interrupt Input: 1 ms (response time)


Positioning function example parameter settings Pulse Output Mode: CW/CCW mode
Rotation Direction Setting:
Current Value Increment with Forward Run Pulse Output


High-speed counter function example parameter settings Pulse Input Mode: 1-Phase Multiple of 1 Counting Speed Setting: 100 kpps

Built-in CPU positioning control function

## Positioning function

The built-in positioning function has a start time of just $30 \mu \mathrm{~s}$ with a maximum high speed output of 200 K pulses per second.
Furthermore, it supports S-curve acceleration and deceleration for applications that require minimal machine vibration.

## High-speed counter function

Two channels support the high speed counting function. The differential line driver inputs support counting speeds up to 200K pulses per second.

Make highly accurate measurements with a resolution of $5 \mu \mathrm{~s}$
High-Speed Counter
Using pulse measurement mode, where the input signal ON/
OFF time is $200 \mu \mathrm{~s}$ or greater, highly accurate measurements in units of $5 \mu \mathrm{~s}$ or greater are possible.
For example it is possible to calculate length by knowing the "work object passing speed" and measuring the ON time of the sensor.


High precision PWM control up to 200 kHz
Using the pulse width modulation control function of the high speed outputs, cycle times as fast as $5 \mu \mathrm{~s}$ can be created. Simply input the ON time and cycle time to drive a wide range of devices from lighting dimmer control, motors, and heaters to precision inspection equipment requiring high resolution performance.

| Setting item | Setting range | Description |
| :---: | :---: | :---: |
| PWM output ON time* ${ }^{\star 1}$ | $\begin{gathered} 0 \text { or } 10 \ldots \\ 10000000^{\star 1}(0.1 \mu \mathrm{~s}) \end{gathered}$ | Set the ON time of output pulse |
| PWM output cycle time*1 | 50...10000000*1 ${ }^{(0.1} \mu \mathrm{s}$ ) | Set the cycle time of output pulse |
| *1: The PWM output ON time must be $\leq$ than PWM output cycle time. |  |  |
|  | PWM output ON time PWM output cycle time | D: Duty Cycle <br> $\tau:$ ON time <br> $\mathrm{T}:$ Cycle time |


*2: In cases where the first six digits of the serial number are "120722" or later. Previous serial numbers of the CPU module are applied to 100 mA .

High-Speed Counter


## Guaranteed input pulse detection

Typical programmable controller input devices are unable to detect pulse signals whose ON time is shorter than the scan time or do not occur during I/O refresh periods. The pulse catch function allows these signals to be reliably detected and passed to the sequence program. This function is different from the interrupt input function in that it does not require any special programming. Pulse catch inputs may be used in programs exactly the same as traditional input $(X)$ signals.


## CPU with built-in CC-Link network connectivity

L26CPU-(P)BT
L Series CC-Link ready CPUs are compatible with the latest generation of CC-Link devices and support connections with over 1,000 different product types. Without adding a module, these CPUs can perform high-speed communication with a maximum of 128 words $^{* 3}$ between a master station and a local station. CC-Link is the dominate FA network standard in Asia and continues to gain support worldwide.

## CC-Link 12



Convenient communication and storage options come as standard

Program, configure, and perform diagnostics on L Series systems using either the USB 2.0 or Ethernet connections. The SD Memory Card slot has many uses including the easy backup and restore of programs and parameters.


USB and Ethernet connections standard

Use the USB 2.0 interface or Ethernet to connect directly at the instillation site. The Ethernet interface supports direct connection with either a cross or straight LAN cable and does not require any configuration of the programmable controller or PC to operate.


Direct connection with straight or cross cable.

Easy connection through hub

All CPUs connected to the same hub can be searched and displayed in a list.
By selecting the access target CPU from the list, it can be connected to even if the IP address is unknown.


Easily connect to BACnet ${ }^{\text {TM }}$ and MODBUS ${ }^{\oplus} / T C P$
Ethernet realizes a high-speed connection, such as communication with external devices.
By using the predefined protocol support function, various devices that require open network protocol support, such as BACnet ${ }^{T \mathrm{M}}$ and MODBUS $\oplus / T C P$ are supported.


## Network timestamp

Synchronize systems on an Ethernet network using an SNTP*1 ${ }^{*}$ server. Time synchronization can be achieved to enable simultaneous operations, quality control, or error tracking.
*1: SNTP: Simple Network Time Protocol


Program-less device data transfer
Simple PLC communication function*2
Using the programming tool, a simple parameter setting is all that is needed to transfer device data such as production information with no programming required.
This function makes it possible to easily establish communications not only with L Series, but also Q Series and QnA/A Series controllers.
*2: CPU module whose first five serial number digits are "13042" or later is required.

| Item |  | Description |
| :---: | :---: | :---: |
| Communication pattern | Read | Read the data of the specified destination device (transmission source) to the specified device of the host station (transmission destination). |
|  | Write | Write the data of the specified device of the host station (transmission source) to the specified destination device (transmission destination). |
|  | Transfer | Read the data of the specified destination device (transmission source) and write it to another specified destination device (transmission destination). |
| Communication setting | Execution interval | Set between 10 ms and 65535 ms (1 ms unit) |
|  | Request contact | Data send/receive is executed at the rising edge (OFF to ON) of the specified device ( $\mathrm{X}, \mathrm{M}, \mathrm{B}$ ). |
| Available devices | Setting No. | Set between 1 and 64. |
|  | Device points | The maximum number that can be set for each setting No. is 512 words. (Maximum points of a word device: 256 points + Maximum points of a bit device: 4096 points) The total of setting No. 1... 64 is maximum 4096 words. |



## SD memory card special features

Use the SD/SDHC compatible memory card to quickly and easily back-up the CPU programs and parameters.
The backups can then be just as easily restored or used to program other CPUs. The memory card can also be used to hold data captured with the data logging function*3.
*3: For details about the data logging function, please refer to page 9.

## Save/load programs directly into the Programmable Controller

## Multiple project save/load function*4

Parameters, program files, etc., can be saved/read onto an SD memory card by simply using the onboard display unit, without having to connect to a separate PC. Once saved on the SD memory card, files can be sent via e-mail, for example, when requiring off-site editing of the files.
*4: Supported by CPU module whose first five serial number digits are " 14042 " or later.



Save space in control panels by utilizing the integrated system bus structure. Flexibility in system design is made possible by choosing only the required expansion modules for the application.

## Expand L Series systems with no base unit restrictions

L Series modules do not require a base unit. The installation space is not restricted by base size, and the system can be installed with minimal required space.
Furthermore, the addition of modules to the system is not restricted by the number of available base unit slots and costs may be reduced due to the elimination of extension base units.


Installation space is reduced in the control panel

## Identify important information easily

Every L Series module has the serial number printed on the front surface of the module to allow viewing even during system operation (modules do not need to be removed).
*: Serial numbers can also be checked using GX Works2.


## System expandable according to production equipment scale

Up to three extension blocks connectable to the main block using branch and extension modules. A maximum of 40 modules ${ }^{\star 1}$ caters a wide range of production equipment and line scale.

| CPU module ${ }^{\text {2 }}$ | Number of extension blocks | Number of connectable modules*3 |
| :---: | :---: | :---: |
| $\begin{aligned} & \hline \text { LO2SCPU(-P) } \\ & \text { LO2CPU(-P) } \end{aligned}$ | Up to 2 blocks |  |
| $\begin{aligned} & \hline \text { L06CPU(-P) } \\ & \text { L26CPU(-P) } \\ & \text { L26CPU-(P)BT } \\ & \hline \end{aligned}$ | Up to 3 blocks | Main block: 10 modules <br> Extension block: 11 modules |

*1: In the case of L06CPU(-P), L26CPU(-P), and L26CPU-(P)BT.
*2: CPU modules whose first five serial number digits are 13072 or later.
*3: Total number of I/O modules, intelligent function modules, network modules and branch modules.
This does not include the following: Power supply, CPU, display units, extension modules, RS-232 adapter, RS-422/485 adapter, and END covers.

[^1]4: Total number of I/O modules, intelligent function modules and network modules, excluding branch modules.

## Well-organized control panel with minimum wiring

Branch module can be strategically placed in a block to minimize wiring space. Extension cables are available in $0.6-, 1.0-$ and $3.0-\mathrm{m}$. The maximum extension length is 3.0 m . .
The extension cable is a one-touch type which can be easily connected and disconnected.
*5: The total length of extension cables should be within 3.0 m .


The modules can be replaced according to the system configuration!


| Modules | Installed block | Possible installation position |
| :---: | :---: | :---: |
| Branch module | Main block | Right side of CPU module or left side of END cover |
|  | Extension block | Right side of extension module or left side of END cover |
| Extension module | Main block | Not applicable |
|  | Extension block | Right side of power supply module |

## Historical trend and live feeds of production

The data logging function*1 embedded in the CPU module allows collected data to be saved in CSV format on an SD memory card simply by using the dedicated setting tool wizard. Additionally, the real-time feature enables live feeds of production data with setup options enabling adjustment of data capture timings.
*1: Not equipped in LO2SCPU(-P).

## Easily collect production data

Utilizing the installed SD memory card or a direct live connection to the CPU module, logging data can be easily realized just by simply registering parameters. Logged data can be saved in CSV format and utilized in a number of ways, such as for using on third-party spreadsheet software or as a real-time feed data for analyzing various manufacturing processes. The real-time feature of GX LogViewer also enables live feeds showing device status changes, helping to improve traceability, smooth startup, and debugging.


## Logging of control data variances

Data is collected during each scan or within millisecond intervals allowing detection of control deviation even at very high speeds. Therefore, identification of errors can be conducted faster and in more detail.

■ Generic sample data from a PC or external device at 100 ms intervals $\square$ Series data logging function is capable of sampling data at much higher intervals as to detect fast changing values.


## Auto logging function

Automatic data logging realized just by inserting the SD memory card into the CPU, which is achieved as the memory card includes the logging configuration file. Instructing data logging remotely is also realized just by sending the configuration file by e-mail and copying onto the SD memory card.

Example: Quickly setup for automatic data logging on-site


## Automatically send logging files to FTP server

Data logging files saved on the SD memory card can be sent to the FTP server just by making a simple setting with the logging configuration tool. As the logging server can handle multiple files, management and maintenance tasks can be reduced.

File transfer feature*1

*1: Using a CPU module with the first 5 digits of the serial number "12112" or later

## Trigger logging function

Error causes and solutions can be quickly done as only the required data related to the problem is extracted, without having to spend time on filtering large volumes of diagnostic data.


To receive a copy of GX LogViewer, contact your local Mitsubishi Electric representative


## Feature rich and easy to use display

Check the system status and make setting changes directly from the display. Error status is clearly identified and troubleshooting and error investigation can be performed all without the need for any connections or engineering software.
*: Not available for LO2SCPU(-P).
L02CPU(-P) L06CPU(-P) L26CPU(-P) L26CPU-(P)BT

Instant error information check
Error history and detailed error information are available directly from the display unit.


## Intuitive menu navigation

The menu navigation guide shows the current menu tree location and an arrow to indicate the scroll direction at the top of the display.


## Multilingual operation

The display unit language can be selected (Japanese or English).


Choose the desired language


Japanese display


English display

## L02CPU

## MODE = ERR. RUN = I/OERR. BAT. USER

| 0 |  |
| :--- | :--- |
| 1 |  |
| 1 |  |
| 2 |  |
| 3 |  |
| 4 | $\vdots$ |
| 5 | $\vdots$ |
| 6 | $\vdots$ |
| 7 | 1 |
|  |  |



An easy-to-use modular design
The L Series module labeling design has been created to ensure clear legibility and identification of information at a glance to avoid mistakes.

## Universal design

## Adopting a universal font

A high visibility font has been chosen for characters printed on system modules.


## Module design

White and red are used to distinguish inputs from outputs respectively to allow for easy identification of terminal connection type.


The characters are thick enough
however the numbers " $3,6,8,9$ " and the alphabet " $C$ " are not clearly distinguishable because the spacing indicated with a red circle is not large enough.

The space indicated with a red circle has been enlarged
The numbers " $3,6,8,9$ " and the
alphabet " $C$ " are clearly distinguishable. Characters are legible even in small print.


Red for output module

## Easily identify module status

LEDs display the current status of modules including run and error states.


## CPU Modules



| Model | General-purpose output | Number of I/O points | Program capacity | Basic operation processing speed (LD instruction) | Peripheral connection ports | Built-in network |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| LO2SCPU | Sink type | 1024 points | 20K steps | 60 ns | USB/RS-232 | - |
| LO2CPU |  |  |  | 40 ns | USB/Ethernet | - |
| L06CPU |  | 4096 points | 60K steps | 9.5 ns |  | - |
| L26CPU |  |  | 260 K steps |  |  | - |
| L26CPU-BT |  |  |  |  |  | CC-Link |
| LO2SCPU-P | Source type | 1024 points | 20K steps | 60 ns | USB/RS-232 | - |
| L02CPU-P |  |  |  | 40 ns | USB/Ethernet | - |
| L06CPU-P |  | 4096 points | 60K steps | 9.5 ns |  | - |
| L26CPU-P |  |  | 260 K steps |  |  | - |
| L26CPU-PBT |  |  |  |  |  | CC-Link |

CPU packages


## ■ General specifications

General specifications indicate the environmental specifications in which this product can be installed and operated. Unless otherwise specified, these general specifications apply to all L Series products.

| Item | Specification |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Operating ambient temperature | $0 \ldots 55^{\circ} \mathrm{C}$ |  |  |  |  |  |
| Storage ambient temperature | $-25 . .75^{\circ} \mathrm{C}$ |  |  |  |  |  |
| Operating ambient humidity | 5...95\%RH, non-condensing |  |  |  |  |  |
| Storage ambient humidity |  |  |  |  |  |  |
| Vibration resistance | Compliant with JIS B 3502 and IEC 61131-2 |  | Frequency | Constant acceleration | Half amplitude | Sweep count |
|  |  | Under intermittent vibration | $5 . .8 .4 \mathrm{~Hz}$ | - | 3.5 mm | 10 times each in $\mathrm{X}, \mathrm{Y}, \mathrm{Z}$ directions |
|  |  |  | 8.4...150 Hz | 9.8 m/ ${ }^{2}$ | - |  |
|  |  | Under continuous vibration | $5 . .8 .4 \mathrm{~Hz}$ | - | 1.75 mm | - |
|  |  |  | 8.4..150 Hz | $4.9 \mathrm{~m} / \mathrm{s}^{2}$ | - |  |
| Shock resistance | Compliant with JIS B 3502 and IEC 61131-2 (147 m/s ${ }^{2}$, 3 times each in directions X, Y, Z) |  |  |  |  |  |
| Operating atmosphere | No corrosive gases |  |  |  |  |  |
| Operating altitude*1 | $0 . .2000 \mathrm{~m}$ |  |  |  |  |  |
| Installation location | Inside a control panel |  |  |  |  |  |
| Overvoltage category*2 | $\leq$ II |  |  |  |  |  |
| Pollution degree*3 | $\leq 2$ |  |  |  |  |  |
| Equipment class | Class I |  |  |  |  |  |

*1: Do not use or store the programmable controller under pressure higher than the atmospheric pressure of altitude 0 m .
Doing so may cause malfunction. When using the programmable controller under pressure, please consult your local Mitsubishi Electric representative
*2: This indicates the section of the power supply to which the equipment is assumed to be connected between the public electrical power distribution network and the machinery within premises.
Category II applies to equipment for which electrical power is supplied from fixed facilities. The surge voltage withstand level for up to the rated voltage of 300 V is 2500 V .
*3: This index indicates the degree to which conductive material is generated in terms of the environment in which the equipment is used
Pollution level 2 is when only non-conductive pollution occurs. A temporary conductivity caused by condensing must be expected occasionally

## ■ CPU module specifications

| Item |  |  | $\begin{aligned} & \text { L02SCPU } \\ & \text { L02SCPU-P } \end{aligned}$ | $\begin{aligned} & \text { L02CPU } \\ & \text { L02CPU-P } \end{aligned}$ | $\begin{aligned} & \text { L06CPU } \\ & \text { L06CPU-P } \end{aligned}$ | $\begin{aligned} & \text { L26CPU } \\ & \text { L26CPU-P } \end{aligned}$ | $\begin{aligned} & \text { L26CPU-BT } \\ & \text { L26CPU-PBT } \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Control method |  |  | Stored program cyclic operation |  |  |  |  |
| I/O control mode |  |  | Refresh mode <br> (The direct access input/output is available by specifying the direct access input/output (DX, DY).) |  |  |  |  |
| Programming language (sequence control language) |  |  | Function block, relay symbol language, MELSAP3 (SFC), MELSAP-L, structured text (ST), logic symbolic language |  |  |  |  |
| Processing speed*4 (sequence instruction) | LD instruction |  | 60 ns | 40 ns | 9.5 ns |  |  |
|  | MOV instruction |  | 120 ns | 80 ns | 19 ns |  |  |
| Constant scan |  |  | $0.5 \ldots 2000 \mathrm{~ms}$ (Setting is available in increments of 0.5 ms by parameter.) |  |  |  |  |
| Program capacity |  |  | 20K steps (80K bytes) |  | 60K steps (240K bytes) | 260K steps (1040K bytes) |  |
| Memory capacity | Program memory (drive 0) |  | 80K bytes |  | 240K bytes | 1040K bytes |  |
|  | Memory card (RAM) (drive 1) |  | - |  |  |  |  |
|  | Memory card (ROM) (drive 2) |  | Depends on the SD/SDHC memory card used.*5 |  |  |  |  |
|  | Standard RAM (drive 3) |  | 128K bytes |  | 768 K bytes |  |  |
|  | Standard ROM (drive 4) |  | 512K bytes |  | 1024K bytes | 2048K bytes |  |
| Maximum number of files stored | Program memory |  | 64 files |  | 124 files | 252 files |  |
|  | Memory card (RAM) |  | - |  |  |  |  |
|  | Memory card (ROM) | SD | Root directory: 511 files (maximum) Subdirectory: 65533 files (maximum) |  |  |  |  |
|  |  | SDHC | Root directory: 65534 files (maximum) Subdirectory: 65533 files (maximum) |  |  |  |  |
|  | Standard RAM |  | 4 files (each one of the following files: file register file, local device file, sampling trace file, and module error collection file) |  |  |  |  |
|  | Standard ROM |  | 128 files |  | 256 files |  |  |
| Maximum number of intelligent function module parameters |  | Initial setting | 2048 parameters |  | 4096 parameters |  |  |
|  |  | Refresh | 1024 parameters |  | 2048 parameters |  |  |
| Maximum number of installable modules ${ }^{* 6}$ |  |  | 30 |  | 40 |  |  |
| Built-in I/O function |  |  | Refer to the built-in I/O specifications $\Rightarrow$ P. 16 to P. 18 |  |  |  |  |
| Data logging function |  |  | Refer to the buitt-in $1 / \mathrm{O}$ specifications $\boldsymbol{\sim}$ ( Pefer to the data logging function specifications $\Rightarrow$ P. 17 |  |  |  |  |
| Built-in Ethernet function |  |  | Refer to the built-in Ethernet specifications $\boldsymbol{\rightarrow}$ P. 18 |  |  |  |  |
| Built-in serial communication function |  |  | Refer to the built-in serial communication specifications $\boldsymbol{=}$ P. 18 | - |  |  |  |
| Built-in CC-Link function |  |  | - |  |  |  | Refer to the CC-Link Master/Local Module specifications. $\Rightarrow$ P. 55 |
| Clock function | Displayed information |  | Year, month, date, hour, minute, second, and day of the week (automatic leap year detection) |  |  |  |  |
|  | Accuracy |  | $\begin{gathered} 0^{\circ} \mathrm{C}:-2.96 \ldots+3.74 \mathrm{~s}(\text { TYP. }+1.42 \mathrm{~s}) \text { per day } \\ \left.25^{\circ} \mathrm{C}:-3.18 \ldots+3.74 \mathrm{~s} \text { (TYP. }+1.50 \mathrm{~s}\right) \text { per day } \\ 55^{\circ} \mathrm{C}:-13.20 \ldots+2.12 \mathrm{~s}(\text { TYP. }-3.54 \mathrm{~s}) \text { per day } \end{gathered}$ |  |  |  |  |
| 5 V DC internal current consumption | CPU | With display unit | - | 1.00 A | 1.06 A |  | 1.43 A |
|  |  | Without display unit | 0.75 A | 0.94 A | 1.00 A |  | 1.37 A |
|  | END cover (Accessory)*7 |  | 0.04 A |  |  |  |  |
| Weight | CPU ${ }^{2}$ | With display unit | - |  | 0.40 kg |  | 0.50 kg |
|  |  | Without display unit | 0.32 kg |  | 0.37 kg |  | 0.47 kg |
|  | END cover (Accessory)* ${ }^{\text {7 }}$ |  | 0.06 kg |  |  |  |  |

*4: Indexing devices does not delay processing time.
*5: The operation of devices that are not manufactured or recommended as compatible products by Mitsubishi Electric cannot be guaranteed.
*6: The total number of modules that can be installed onto a CPU module. Also refer to the "Module size allocation" for each module.
(Power supply modules, CPU module, Display unit, Extension module, RS-232 adapter, RS-422/485 adapter, END cover,
and END cover with error terminal are not included. Note that only one CPU per system is possible.)
*7: The END cover is included with the CPU module and must be placed on the right end of the last module in the system.

| Item |  | $\begin{aligned} & \text { L02SCPU } \\ & \text { L02SCPU-P } \end{aligned}$ | $\begin{aligned} & \text { L02CPU } \\ & \text { LO2CPU-P } \end{aligned}$ | $\begin{aligned} & \text { L06CPU } \\ & \text { L06CPU-P } \end{aligned}$ | $\begin{aligned} & \text { L26CPU } \\ & \text { L26CPU-P } \end{aligned}$ | L26CPU-BT L26CPU-PBT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Number of I/O device points (number of points available on a program) |  | 8192 points (X/YO...X/Y1FFF) |  |  |  |  |
| Number of I/O points |  | 1024 points (X/Y0...X/Y3FF) |  | 4096 points (X/YO...X/YFFF) |  |  |
| Internal relay (M) |  | 8192 points (M0...M8191) by default (changeable) |  |  |  |  |
| Latch relay (L) |  | 8192 points (LO...L8191) by default (changeable) |  |  |  |  |
| Link relay (B) |  | 8192 points (B0...B1FFF) by default (changeable) |  |  |  |  |
| Timer ( T ) |  | 2048 points (TO...T2047) by default (changeable) (Low-speed and high-speed timers available) (Low-speed timer: $1 \ldots 1000 \mathrm{~ms}$ (in increments of 1 ms ), default: 100 ms ) (High-speed timer: $0.1 \ldots 100 \mathrm{~ms}$ (in increments of 0.1 ms ), default: 10 ms ) |  |  |  |  |
| Retentive timer (ST) |  | 0 point by default (changeable)(Low-speed and high-speed retentive timers available) (Low-speed retentive timer: $1 \ldots .1000 \mathrm{~ms}$ (in increments of 1 ms ), default: 100 ms ) (High-speed retentive timer: $0.1 \ldots 100 \mathrm{~ms}$ (in increments of 0.1 ms ), default: 10 ms ) |  |  |  |  |
| Counter (C) |  | Normal counter 1024 points (C0...C1023) by default (changeable) |  |  |  |  |
| Data register (D) |  | 12288 points (DO...D12287) by default (changeable) |  |  |  |  |
| Extended data register (D) |  | 32768 points (D12288...D45055) by default (changeable) |  | 131072 points (D12288...D143359) by default(changeable) |  |  |
| Link register (W) |  | 8192 points (W0...W1FFF) by default (changeable) |  |  |  |  |
| Extended link register (W) |  | 0 point by default (changeable) |  |  |  |  |
| Annunciator (F) |  | 2048 points (FO...F2047) by default (changeable) |  |  |  |  |
| Edge relay (V) |  | 2048 points (V0...V2047) by default (changeable) |  |  |  |  |
| Link special relay (SB) |  | 2048 points (SB0...SB7FF) by default (changeable) |  |  |  |  |
| Link special register (SW) |  | 2048 points (SW0...SW7FF) by default (changeable) |  |  |  |  |
| File register | (R) | 32768 points (R0...R32767) (Maximum 65536 points are available by switching blocks.) |  | 32768 points (RO...R32767) <br> (Maximum 393216 points are available by switching blocks.) |  |  |
|  | (ZR) | 65536 points (ZRO...ZR65535) (Blocks do not need to be switched.) |  | 393216 points (ZR0...ZR393215) <br> (Blocks do not need to be switched.) |  |  |
| Step relay (S) |  | 8192 points (S0...S8191) by default |  |  |  |  |
| Index register/standard device register (Z) |  | 20 point (Z0...Z19) (maximum) |  |  |  |  |
| Index register (Z) <br> (32-bit index modification of ZR device) |  | 10 point (Z0...Z18) (maximum)(The index register is used as a double-word device.) |  |  |  |  |
| Pointer (P) |  | 4096 points (P0...P4095) (The local pointer range and the common pointer range can be set by parameter.) |  |  |  |  |
| Interrupt pointer (I) |  | 256 points (10...1255) <br> (The fixed scan interval for the system interrupt pointer I28...I31 can be set by parameter.) <br> $0.5 \ldots .1000 \mathrm{~ms}$ (in increments of 0.5 ms ) <br> Default I28: $100 \mathrm{~ms}, \mathrm{I} 29: 40 \mathrm{~ms}, \mathrm{I} 30: 20 \mathrm{~ms}, \mathrm{I} 31: 10 \mathrm{~ms}$ |  |  |  |  |
| Special relay (SM) |  | 2048 points (SM0...SM2047) (The number of device points is fixed.) |  |  |  |  |
| Special register (SD) |  | 2048 points (SDO...SD2047) (The number of device points is fixed.) |  |  |  |  |
| Function input (FX) |  | 16 points (FXO...FX F) (The number of device points is fixed.) |  |  |  |  |
| Function output (FY) |  | 16 points (FYO...FY F) (The number of device points is fixed.) |  |  |  |  |
| Function register (FD) |  | 5 points (FDO...FD4) (The number of device points is fixed.) |  |  |  |  |
| Intelligent function module device |  | Device that directly accesses the buffer memory of an intelligent function module Specification format: $\square$ |  |  |  |  |
| Latch (data retention during power failure) range |  | 8192 points (LO...L8191) by default range can be set for the devices, B, F, V, T, ST, C, D, W, and R by parameter.) |  |  |  |  |



■ CPU built-in I/O function - output specifications (general-purpose output function)


CPU built-in I/O function - positioning function specifications

| Item |  |  | Description |
| :---: | :---: | :---: | :---: |
| Number of controlled axes |  |  | 2 |
| Control unit |  |  | pulse |
| Operation pattern |  | PTP*1 control | Available |
|  |  | Path control | Not usable |
| Number of positioning data |  |  | 10 data/axis |
| Positioning control | Positioning control method | PTP*1 control | ABS/INC |
|  |  | Speed/position switching control | INC |
|  | Positioning range | PTP*1 control | -2147483648... 2147483647 pulses |
|  |  | Speed/position switching control | 0... 2147483647 pulses |
|  | Speed command |  | 0...200k pulses/s |
|  | Acceleration/deceleration system selection |  | Automatic trapezoid acceleration/deceleration and S-curve acceleration/deceleration |
|  | Acceleration/deceleration time |  | $0 . .32767 \mathrm{~ms}$ |
| OPR method |  |  | 6 types |
| Starting time (1-axis linear control) |  |  | Trapezoid acceleration/deceleration (single-axis start): $30 \mu \mathrm{~s} / \mathrm{axis}$ S-curve acceleration/deceleration (single-axis start): $35 \mu \mathrm{~s} /$ axis |
| Command pulse output | Pulse output method |  | L02SCPU, L02CPU, L06CPU, L26CPU, L26CPU-BT: 5...24V DC (Sink type) L02SCPU-P, L02CPU-P, L06CPU-P, L26CPU-P, L26CPU-PBT: 5...24V DC (Source type) |
|  | Pulse output mode |  | 4 types |
|  | Maximum output pulse |  | 200k pulses/s |
|  | Maximum connection distance with drive unit |  | 2 m |
| External input | Zero signal | DC input | 24 V DC 6.0 mA (TYP.) |
|  |  | Differential input | EIA RS-422-A differential line driver level <br> AM26L31 (manufactured by Texas Instruments Incorporated) or equivalent |
|  | Speed/position switching signal |  | 24 V DC 4.1 mA (TYP.) |
|  | Near-point dog signal |  |  |
|  | Upper and lower limit signal |  |  |
|  | Drive unit ready signal |  |  |
|  | Input response time |  | Zero signal: $10 \mu \mathrm{~s}$ <br> Speed/position switching control, near-point dog signal: $100 \mu \mathrm{~s}$ Upper and lower limit signal, drive unit ready signal: 2 ms |
| External output | Deviation counter clear signal |  | L02SCPU, L02CPU, L06CPU, L26CPU, L26CPU-BT: $5 . . .24$ V DC 0.1A (Sink type) L02SCPU-P, L02CPU-P, L06CPU-P, L26CPU-P, L26CPU-PBT: 5... 24 V DC 0.1A (Source type) |
|  | Response time | OFF to ON | $\leq 1 \mu \mathrm{~s}$ (rated load, resistive load) |
|  |  | ON to OFF |  |

*1: Abbreviation for "Point to Point." This is a type of position control.

■ CPU built-in I/O function - high-speed counter specifications

|  | Item |  | Description |
| :---: | :---: | :---: | :---: |
| Number of channels |  |  | 2 |
| Count input signal | Phase |  | 1-phase input (1 multiple/2 multiples) CW/CCW, <br> 2-phase input (1 multiple/2 multiples/4 multiples) |
|  | Signal level | DC input | 24 V DC 6.0 mA (TYP.) |
|  |  | Differential input | EIA Standard RS-422-A Differential line driver level <br> AM26L31 (manufactured by Texas Instruments Incorporated) or equivalent |
| Counter | Maximum counting speed |  | 200 k pulses/s (for 2 multiples of 1 phase and 4 multiples of 2 phases) |
|  | Counting range |  | -2147483648... 2147483647 |
|  | Model |  | UP/DOWN preset counter (with ring counter function) |
|  | Minimum count pulse width (Duty ratio 50\%) | 1 phase | $5 \mu \mathrm{~s}$ |
|  |  | 2 phases | $10 \mu \mathrm{~s}$ |
|  | Min. phase differential for 2-phase input |  | $5 \mu \mathrm{~s}$ |
| External input | Phase Z (preset) | DC input | 24 V DC 6.0 mA (TYP.) |
|  |  | Differential input | EIA Standard RS-422-A Differential line driver level <br> AM26L31 (manufactured by Texas Instruments Incorporated) or equivalent |
|  | Function start |  | 24 V DC 4.1 mA (TYP.) |
|  | Latch |  |  |
|  | Input response time |  | Phase Z: $10 \mu \mathrm{~s}$ <br> Function start, latch: $100 \mu \mathrm{~s}$ |
| External output | Output format |  | L02SCPU, L02CPU, L06CPU , L26CPU, L26CPU-BT: Sink type L02SCPU-P, L02CPU-P, L06CPU-P, L26CPU-P, L26CPU-PBT: Source type |
|  | Output voltage/current | Coincidence output No. 1 PWM output | 5... 24 V DC/0.25 $\mathrm{A}^{* 1}$ |
|  |  | Coincidence output No. 2 | 5... 24 V DC/0.1 A |
|  | Response time | OFF to ON | $\leq 1 \mu$ (Rated load, resistance load) |
|  |  | ON to OFF |  |
| Coincidence output | Comparison range |  | -2147483648...2147483647 |
|  | Comparison result |  | Set value < Counted value <br> Set value = Counted value <br> Set value > Counted value |
|  | Output points |  | 2 points/channel |
| PWM output | Output frequency range |  | DC... 200 kHz |
|  | ON width |  | $1 \mu \mathrm{~s}$ |
|  | Duty ratio |  | On width can be set in increments of $0.1 \mu \mathrm{~s}$. |
|  | Output points |  | 1 point/channel |
| Pulse width measurement | Measurement item |  | Pulse width (On width: $\geq 200 \mu \mathrm{~s}$, Off width: $\geq 200 \mu \mathrm{~s}$ ) |
|  | Measurement resolution |  | $5 \mu \mathrm{~s}$ |
|  | Measurement points |  | 1 point/channel |

*1: For units where the first six digits of the serial number are "120722" or later. The specification for previous serial numbers is 5 to $24 \mathrm{VDC/0.1} \mathrm{~A}$.

## ■ CPU data logging function specifications


*2: Part of the saved file name, this number is automatically assigned.
*3: Optional data to be appended to the saved file name.

■ CPU built-in Ethernet function specifications

| Item |  |  | LO2CPU <br> L02CPU-P | L06CPU L06CPU-P | $\begin{aligned} & \text { L26CPU } \\ & \text { L26CPU-P } \end{aligned}$ | L26CPU-BT L26CPU-PBT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Transmission specifications | Data transfer speed |  | 100 or 10 Mbps |  |  |  |
|  | Communication mode |  | Full-duplex or half-duplex |  |  |  |
|  | Transmission method |  | Base band |  |  |  |
|  | Maximum distance between hub and node |  | 100 m |  |  |  |
|  | Maximum number of nodes/connection | 10BASE-T | Cascade connection: Up to four |  |  |  |
|  |  | 100BASE-TX |  | Casca | to two |  |
|  | TCP/IP |  | Total of 16 for socket communications, MELSOFT connections, and MC protocol.*1One for FTP |  |  |  |
| connections | UDP/IP |  |  |  |  |  |
| Connection | 10BASE-T |  | Ethernet cable of category 3 or higher (STP/UTP cable)*3 |  |  |  |
| cable*2 | 100BASE-TX |  | Ethernet cable of category 5 or higher (STP cable) |  |  |  |

*1: Only the QnA-compatible 3E frame may be used.
*2: Standard (straight type) cable. Also, when the CPU is connected directly with a GOT(HMI), a cross cable (category 5 e or less) may be used.
*3: The use of STP (Shielded Twisted Pair) cables is recommended in noisy environments.
■ Communication performance comparison (Comparison of LCPU with built-in Ethernet port and Ethernet interface module)

| Function/performance | LCPU with built-in Ethernet port | Ethernet interface module |
| :--- | :---: | :---: |
| Communication speed | 100 Mbps | 100 Mbps |
| MC protocol communication | $\bullet^{* 4}$ | $\bullet$ |
| Socket communication | $\bullet * 5$ | $\bullet$ |
| Communications using a random access buffer | - | $\bullet$ |
| E-mail function | - | $\bullet$ |
| Communications using data link instructions | - | $\bullet$ |
| File transfer (FTP server) function | $\bullet *$ | $\bullet$ |
| Web function | - | $\bullet$ |
| MELSOFT products and GOT(HMI) connection | $\bullet$ | $\bullet$ |

*4: QnA compatible 3E frame device memory access commands only. Refer to the relevant manual for details.
*5: There are some differences regarding the fixed buffer communications function. Refer to the relevant manual for details.
*6: The "quote cpuchg" command is not supported.
■ CPU built-in serial communication function specifications


- How to read the product code

L 26 $\square$ CPU - P BT - SET

| Number | Item | Code | Specification |
| :---: | :---: | :---: | :---: |
| (1) | Program memory capacity | 02 | 20K steps |
|  |  | 06 | 60 K steps |
|  |  | 26 | 260 K steps |
| Number | Item | Code | Specification |
| (2) | Communication interface | Blank | Built-in Ethernet model |
|  |  | S | Built-in RS-232 model |
| Number | Item | Code | Specification |
| (3) | Type of module | CPU | CPU module |
| Number | Item | Code | Specification |
| (4) | Built-in I/O output format | Blank | Sink type |
|  |  | P | Source type |
| Number | Item | Code | Specification |
| (5) | Built-in CC-Link function | Blank | - |
|  |  | BT | $\bullet$ |
| Number | Item | Code | Specification |
| © | Product set | Blank | - |
|  |  | SET | Set includes a power supply module (L61P) and display unit (L6DSPU) |

## Branch/Extension Modules



■ Branch and extension module specifications

| Item | L6EXB |  | L6EXE [ Extension module ] |
| :---: | :---: | :---: | :---: |
| 5 V DC internal current consumption | 0.08 A |  | 0.08 A |
| Weight | 0.12 kg |  | 0.13 kg |
| ■ Extension cable specifications |  |  |  |
| Item | LC06E | LC10E | LC30E |
| Cable length | 0.6 m | 1.0 m | 3.0 m |
| Weight | 0.19 kg | 0.23 kg | 0.45 kg |

## Power Supply Modules



■ Power supply module specifications

| Item | L61P | L63P | L63SP |
| :---: | :---: | :---: | :---: |
| Input power supply | 100...240 V AC (-15\% ...+10\%) | 24 V DC (-35\%...+30\%) |  |
| Input frequency | $50 / 60 \mathrm{~Hz}(-5 \% \ldots+5 \%)$ | - |  |
| Input voltage distortion | $\leq 5 \%$ | - |  |
| Maximum input apparent power | 130 VA | - |  |
| Maximum input power | - | 45 W |  |
| Inrush current | $20 \mathrm{~A}, \leq 8 \mathrm{~ms}$ | $100 \mathrm{~A}, \leq 1 \mathrm{~ms} \mathrm{(24} \mathrm{~V} \mathrm{DC} \mathrm{input)}$ |  |
| Rated output current (5 V DC) | 5 A |  |  |
| Overcurrent protection (5 V DC) | $\geq 5.5 \mathrm{~A}$ |  |  |
| Overvoltage protection | 5.5...6.5 V |  |  |
| Efficiency | $\geq 70 \%$ |  |  |
| Allowable momentary power failure time | $\leq 10 \mathrm{~ms}$ | $\leq 10 \mathrm{~ms}$ (24 V DC input) |  |
| Withstand voltage | 2300 V AC per minute <br> (altitude 0... 2000 m ) <br> Between the combined <br> "line input/LG terminals" <br> and the "FG terminal and output". | 510 V AC per minute (altitude 0... 2000 m ) <br> Between the combined <br> "line input/LG terminals" <br> and the "FG terminal and output". | -*1 |
| Insulation resistance | $10 \mathrm{M} \Omega$ or higher by 500 V DC insulation resistance tester <br> - Between the combined "line input/LG terminals" and the "FG terminal and output". <br> - The line input and LG terminals. <br> - The FG terminal and output. |  | -*1 |
| Weight | 0.32 kg | 0.29 kg | 0.19 kg |

[^2]RS-232 Adapter


L6ADP-R2
Transmission speed: $115.2 \mathrm{kbps} \quad$ Predefined protocol support function GOT(HMI) connection MELSOFT ${ }^{\text {1 }}$ connection Serial communication function

## MODBUS ${ }^{\circledR}$

*1: Please refer to each MELSOFT product manual for details on the supported software

| Item | Specification |
| :---: | :---: |
| Maximum data transmission speed | 115.2 kbps |
| 5 V DC internal current consumption | 0.02 A |
| Weight | 0.10 kg |

## RS-422/485 Adapter



L6ADP-R4
$\begin{array}{ll}\text { Transmission speed: } 115.2 \mathrm{kbps} & \begin{array}{l}\text { Predefined protocol support function } \\ \text { GOT(HMI) connection }\end{array} \\ \text { Serial Communication function }\end{array}$ MODBUS ${ }^{\circledR}$

RS-422/485 adapter specifications

| Item | Specification |
| :--- | :---: |
| Maximum data transmission speed | 115.2 kbps |
| 5 V DC internal current consumption | 0.15 A |
| Weight | 0.12 kg |

## END Cover with Error Terminal



| Item |  |  | Specification |
| :---: | :---: | :---: | :---: |
| ERR. terminal | Rated switching voltage, current |  | 24 V DC 0.5 A |
|  | Minimum switching load |  | 5 V DC, 1 mA |
|  | Response time | OFF to ON | $\leq 10 \mathrm{~ms}$ |
|  |  | ON to OFF | $\leq 12 \mathrm{~ms}$ |
|  | Life | Mechanical | $\geq 20$ million times |
|  |  | Electrical | Rated switching voltage/current: 10 million times or more |
|  | Surge suppressor |  | - |
|  | Fuse |  | - |
| Applicable wire size |  |  | 0.3...2.0 mm² (AWG22...14) (Twisted wire/Solid wire) |
| External interface |  |  | Spring clamp terminal block |
| 5 V DC internal current consumption |  |  | 0.06 A |
| Weight |  |  | 0.11 kg |

## Display Unit



## ■ Display Unit specifications

| Item | Specification |
| :---: | :---: |
| Number of displayed characters | 16 one-byte characters $\times 4$ lines |
| Displayed characters | - Alphanumeric (two-byte/one-byte character) <br> - Japanese character Katakana (two-byte/one-byte character) <br> - Japanese character Hiragana (two-byte character) <br> - Chinese character (two-byte character) <br> - Symbol (two-byte/one-byte character) |
| Language | Japanese/English |
| Backlight | Green (normal), red (error) |
| Weight | 0.03 kg |

## Input Modules



## Output Modules



## I/O Combined Modules



## Spring clamp terminal block (push-in type): L6TE-18S

The screw terminal block of installed modules can be replaced with a push-in type spring clamp terminal block. This terminal block type helps to reduce the amount of wiring and maintenance time.

■ Push-in type for reduced wiring
Easier to wire just by inserting into the terminal block.


- Simple to confirm signal integrity
Includes dedicated terminals for insertion of a test probe, for example.


| ■ Input module specifications |
| :--- |
| AC input module |
| Item |
| Number of input points |
| Rated input voltage, frequency |
| Input voltage distortion |

## DC input module

| Item | LX40C6 | LX41C4 | LX42C4 |
| :---: | :---: | :---: | :---: |
| Number of input points | 16 points | 32 points | 64 points |
| Rated input voltage | 24 V DC (ripple rate: $\leq 5 \%$ ) (allowable voltage range: $20.4 \ldots 28.8 \mathrm{~V} \mathrm{DC)}$ |  |  |
| Rated input current | $6.0 \mathrm{~mA} \mathrm{TYP}. \mathrm{(at} 24 \mathrm{~V}$ DC) | 4.0 mA TYP. (at 24 V DC) |  |
| ON voltage/ON current | $\geq 15 \mathrm{VDC} / \geq 4 \mathrm{~mA}$ | $\geq 19 \mathrm{~V} \mathrm{DC/} 2 \mathrm{3} \mathrm{mA}$ |  |
| OFF voltage/OFF current | $\leq 8 \mathrm{VDC} / \leq 2 \mathrm{~mA}$ | $\leq 9 \mathrm{VDC} / \leq 1.7 \mathrm{~mA}$ |  |
| Input resistance | $3.8 \mathrm{k} \Omega$ | $5.7 \mathrm{k} \Omega$ |  |
| Response time ${ }^{\text {O }}$ OFF to ON | $1 \mathrm{~ms}, 5 \mathrm{~ms}, 10 \mathrm{~ms}, 20 \mathrm{~ms}, 70 \mathrm{~ms}$ or less Initial setting is 10 ms . |  |  |
| ON to OFF |  |  |  |
| Common terminal arrangement | 16 points/common | 32 points/common |  |
| Module size allocation | 1 |  |  |
| Number of occupied I/O points | 16 points (I/O allocation: input 16 points) | 32 points (1/O assignment: input 32 points) | 64 points (I/O allocation: input 64 points) |
| External interface | 18-point terminal block | 40-pin connector | 40-pin connector $\times 2$ |
| 5 V DC internal current consumption | 90 mA (TYP. all points ON) | 100 mA (TYP. all points ON) | 120 mA (TYP. all points ON) |
| Weight | 0.15 kg | 0.11 kg | 0.12 kg |

■ Output module specifications
Contact output module

|  | Item | LY10R2 |  | LY18R |
| :---: | :---: | :---: | :---: | :---: |
| Number of output points |  | 16 points |  | 8 poin |
| Rated switching voltage, current |  | 24 V DC 2 A (resistive load)/point, $8 \mathrm{~A} /$ common 240 V AC 2 A (COS $\phi=1$ )/point, 8 A/common |  | DC 2 A (resistive load) <br> 0 V AC 2 A (COS $\phi=1$ |
| Minimum switching load |  | 5 V DC 1 mA |  |  |
| Maximum switching load |  | 264 V AC 125 V DC |  |  |
| Response time | OFF to ON | $\leq 10 \mathrm{~ms}$ |  |  |
|  | ON to OFF | $\leq 12 \mathrm{~ms}$ |  |  |
| Life | Mechanical | $\geq 20$ million times |  |  |
|  | Electrical | Usage environment |  | Switching life |
|  |  | Rated switching voltage/current, rated load |  | 100 thousand times |
|  |  | 200 V AC 1.5 A, 240 V AC 1 A ( $\operatorname{COS} \phi=0.7$ ) |  | 100 thousand times |
|  |  | 200 V AC $0.4 \mathrm{~A}, 240 \mathrm{~V}$ AC $0.3 \mathrm{~A}(\operatorname{COS} \phi=0.7)$ |  | 300 thousand times |
|  |  | 200 V AC $1 \mathrm{~A}, 240 \mathrm{~V}$ AC $0.5 \mathrm{~A}(\operatorname{COS} \phi=0.35)$ |  | 100 thousand times |
|  |  | 200 V AC $0.3 \mathrm{~A}, 240 \mathrm{~V} \mathrm{AC} 0.15 \mathrm{~A}(\operatorname{COS} \phi=0.35)$ |  | 300 thousand times |
|  |  | 24 V DC $1 \mathrm{~A}, 100 \mathrm{~V}$ DC 0.1 A (L/R $=7 \mathrm{~ms}$ ) |  | 100 thousand times |
|  |  | 24 V DC $0.3 \mathrm{~A}, 100 \mathrm{~V}$ DC $0.03 \mathrm{~A}(\mathrm{~L} / \mathrm{R}=7 \mathrm{~ms})$ |  | 300 thousand times |
| Maximum switching frequency |  | 3600 times/hour |  |  |
| Surge suppressor |  | - |  |  |
| Fuse |  |  | (a fuse is recommended to be installed for each external wiring point) |  |
| Common terminal arrangement |  | 16 points/common |  | No common (all poin |
| Module size allocation |  | 110 |  |  |
| Number of occupied I/O points |  | 16 points (l/O assignment: 16 output points) |  |  |
| External interface |  | 18-point terminal block |  |  |
| 5 V DC internal current consumption |  | 460 mA (TYP. all points ON) | 260 mA (TYP.all points ON) |  |
| Weight |  | 0.21 kg | 0.18 kg |  |

## ■ Output module specifications

## Triac output

| Item |  | LY20S6 | LY28S1A |
| :---: | :---: | :---: | :---: |
| Number of output points |  | 16 points | 8 points |
| Rated load voltage, frequency |  | $100 \ldots 240 \mathrm{~V} \mathrm{AC} \mathrm{(+10} \mathrm{\% /-15} \mathrm{\%)} ,50 / 60 \mathrm{~Hz}( \pm 3 \mathrm{~Hz})$ |  |
| Maximum load current |  | $0.6 \mathrm{~A} /$ point, $4.8 \mathrm{~A} / \mathrm{common}$ | $1 \mathrm{~A} /$ point, $8 \mathrm{~A} / \mathrm{m}$ |
| Load voltage distortion ratio |  | $\leq 5 \%$ |  |
| Maximum load |  | 264 V AC |  |
| Minimum load voltage/current |  | $24 \mathrm{~V} \mathrm{AC/100} \mathrm{mA} ,100 \mathrm{~V} \mathrm{AC/25} \mathrm{mA} ,240 \mathrm{~V} \mathrm{AC/25} \mathrm{~mA}$ |  |
| Maximum inrush current |  | $\leq 20 \mathrm{~A} / \mathrm{cycle}$ |  |
| Leakage current at OFF |  | $\leq 3 \mathrm{~mA}($ at $240 \mathrm{~V}, 60 \mathrm{~Hz}), \leq 1.5 \mathrm{~mA}$ (at $120 \mathrm{~V}, 60 \mathrm{~Hz}$ ) |  |
| Maximum voltage drop at ON |  | $\leq 1.5 \mathrm{~V}$ (at load current of 0.6 A) |  |
| Response time | OFF to ON | Total of 1 ms and 0.5 cycles or less |  |
|  | ON to OFF | Total of 1 ms and 0.5 cycles or less (rated load, resistive load) |  |
| Surge suppressor |  | CR absorber |  |
| Fuse |  | None (Attaching a fuse to each external wiring is recommended.) |  |
| Common terminal arrangement |  | 16 points/common | No common (all points |
| Module size allocation |  | 1 |  |
| Number of occupied I/O points |  | 16 points (//O assignment: output 16 points) |  |
| External interface |  | 18-point terminal block |  |
| 5 V DC internal current consumption |  | 300 mA (TYP. all points ON) | 200 mA (TYP. all po |
| Weight |  | 0.22 kg | 0.19 kg |

Transistor output (Sink type)

| Item |  | LY40NT5P | LY41NT1P | LY42NT1P |
| :---: | :---: | :---: | :---: | :---: |
| Number of output points |  | 16 points | 32 points | 64 points |
| Rated load voltage |  | 10.2...28.8 V DC |  |  |
| Maximum load current |  | 0.5 A/point, $5 \mathrm{~A} /$ common | 0.1 A/point, $2 \mathrm{~A} /$ common |  |
| Maximum inrush current |  | Current is limited by the overload protection function. |  |  |
| Leakage current at OFF |  | $\leq 0.1 \mathrm{~mA}$ |  |  |
| Maximum voltage drop at ON |  | 0.2 V DC(TYP.) 0.5 A , 0.3 V D(MAX.) 0.5 A | $\begin{aligned} & 0.1 \mathrm{VDC} \text { (TYP.) } 0.1 \mathrm{~A}, \\ & 0.2 \mathrm{VDC} \text { (MAX.) } 0.1 \mathrm{~A} \\ & \hline \end{aligned}$ |  |
| Response time | OFF to ON | $\leq 0.5 \mathrm{~ms}$ |  |  |
|  | ON to OFF | $\leq 1 \mathrm{~ms}$ (rated load, resistance load) |  |  |
| Surge suppressor |  | Zener diode |  |  |
| Fuse |  | - |  |  |
| External power supply | Voltage | $12 / 24 \mathrm{~V} \mathrm{DC} \mathrm{(ripple} \mathrm{rate:} \leq 5 \%$ ) (allowable voltage range: $10.2 \ldots 28.8 \mathrm{~V} \mathrm{DC})$ |  |  |
|  | Current | 9 mA (at $24 \mathrm{~V} \mathrm{DC)/common}$ | 13 mA (at $24 \mathrm{~V} \mathrm{DC)/common}$ | 9 mA (at $24 \mathrm{~V} \mathrm{DC)/common}$ |
| Common terminal arrangement |  | 16 points/common | 32 points/common |  |
| Module size allocation |  | [1 1 |  |  |
| Number of occupied I/O points |  | 16 points (I/O assignment: 16 output points) | 32 points (//O assignment: 32 output points) | 64 points (I/O assignment: 64 output points) |
| Protection function | Overload protection | Limited current when detecting overcurrent (overload protection): 1.5...3.5 A/point. <br> Activated in increments of 1 point. | Limited current when detecting overcurrent (overload protection): $1 \ldots 3 \mathrm{~A} /$ point. Activated in increments of 1 point. |  |
|  | Overheat protection | Activated in increments of 1 point |  |  |
| External interface |  | 18-point terminal block | 40-pin connector | 40-pin connector $\times 2$ |
| 5 V DC internal current consumption |  | 100 mA (TYP. all points ON) | 140 mA (TYP. all points ON) | 190 mA (TYP. all points ON) |
| Weight |  | 0.15 kg | 0.11 kg | 0.12 kg |

Transistor output (Source type)

|  | Item | LY40PT5P | LY41PT1P | LY42PT1P |
| :---: | :---: | :---: | :---: | :---: |
| Number of output points |  | 16 points | 32 points | 64 points |
| Rated load voltage |  | 10.2...28.8 V DC |  |  |
| Maximum load current |  | 0.5 A/point, $5 \mathrm{~A} / \mathrm{common}$ | 0.1 A/point, $2 \mathrm{~A} / \mathrm{common}$ |  |
| Maximum inrush current |  | Current is limited by the overload protection function. |  |  |
| Leakage current at OFF |  | $\leq 0.1 \mathrm{~mA}$ |  |  |
| Maximum voltage drop at ON |  | 0.2 V DC(TYP.) 0.5 A , <br> $0.3 \mathrm{VDC}(\mathrm{MAX})$. | 0.1 V DC (TYP.) 0.1 A , 0.2 V DC (MAX.) 0.1 A |  |
| Response time | OFF to ON | $\leq 0.5 \mathrm{~ms}$ |  |  |
|  | ON to OFF | $\leq 1 \mathrm{~ms}$ (rated load, resistance load) |  |  |
| Surge suppressor |  | Zener diode |  |  |
| Fuse |  | - |  |  |
| External power supply | Voltage | $12 / 24 \mathrm{~V} \mathrm{DC} \mathrm{(ripple} \mathrm{rate:} \leq 5 \%$ ) (allowable voltage range: $10.2 \ldots 28.8 \mathrm{~V} \mathrm{DC})$ |  |  |
|  | Current | 17 mA (at 24 V DC)/common | 20 mA (at | C)/common |
| Common terminal arrangement |  | 16 points/common | 32 points/common |  |
| Module size allocation |  | 1 |  |  |
| Number of occupied I/O points |  | 16 points (//O assignment: 16 output points) | 32 points (I/O assignment: 32 output points) | 64 points (I/O assignment: 64 output points) |
| Protection function | Overload protection | Overcurrent detection: $\geq 1.5 \mathrm{~A} /$ point. Activated in increments of 1 point. | Limited current when detecting overcurrent (overload protection): <br> 1... $3 \mathrm{~A} /$ point. <br> Activated in increments of 1 point. |  |
|  | Overheat protection | Activated in increments of 1 point. | Activated in increments of 2 points. |  |
| External interface |  | 18-point terminal block | 40-pin connector | 40-pin connector $\times 2$ |
| 5 V DC internal current consumption |  | 100 mA (TYP. all points ON) | 140 mA (TYP. all points ON) | 190 mA (TYP. all points ON) |
| Weight |  | 0.15 kg | 0.11 kg | 0.12 kg |

■ I/O combined module specifications
DC input/transistor output combined module

| Item |  | LH42C4NT1P | LH42C4PT1P |
| :---: | :---: | :---: | :---: |
| - Input specifications |  |  |  |
| Number of input points |  | 32 points |  |
| Rated input voltage |  | 24 V DC (ripple rate: $\leq 5 \%$ ) (allowable voltage range: $20.4 \ldots 28.8 \mathrm{~V} \mathrm{DC}$ ) |  |
| Rated input current |  | 4.0 mA TYP. (at 24 V DC ) |  |
| Input ON voltage/ON current |  | $\geq 19 \mathrm{~V} \mathrm{DC/} \geq 3 \mathrm{~mA}$ |  |
| Input OFF voltage/OFF current |  | $\leq 9 \mathrm{VDC} / \leq 1.7 \mathrm{~mA}$ |  |
| Input resistance |  | $5.7 \mathrm{k} \Omega$ |  |
| Input response time | OFF to ON | $1 \mathrm{~ms}, 5 \mathrm{~ms}, 10 \mathrm{~ms}, 20 \mathrm{~ms}, 70 \mathrm{~ms}$ or less (Initial setting is 10 ms ) |  |
|  | ON to OFF |  |  |
| Input common terminal arrangement |  | 32 points/common |  |
| - Output specifications |  |  |  |
| Output format |  | Transistor output combined module (Sink type) | Transistor output combined module (Source type) |
| Number of output points |  | 32 points |  |
| Rated load voltage |  | $10.2 \ldots . .28 .8 \mathrm{~V}$ DC |  |
| Maximum load current |  | 0.1 A/point, $2 \mathrm{~A} / \mathrm{common}$ |  |
| Maximum inrush current |  | Current is limited by the overload protection function. |  |
| Leakage current at OFF |  | $\leq 0.1 \mathrm{~mA}$ |  |
| Maximum voltage drop at ON |  | 0.1 V DC (TYP.) 0.1 A , 0.2 V DC (MAX.) 0.1 A |  |
| Output response time | OFF to ON | $\leq 0.5 \mathrm{~ms}$ |  |
|  | ON to OFF | $\leq 1 \mathrm{~ms}$ (rated load, resistance load) |  |
| Surge suppressor |  | Zener diode |  |
| Fuse |  | - |  |
| Protection function | Overload protection | Limited current when detecting overcurrent (overload protection): $1 \ldots 3 \mathrm{~A} /$ point, activated in increments of 1 point |  |
|  | Overheat protection | Activated in increments of 1 point | Activated in increments of 2 points |
| Output common terminal arrangement |  | 32 points/common |  |
| - Common specifications |  |  |  |
| External power supply | Voltage | $12 / 24 \mathrm{~V}$ DC (ripple rate: $\leq 5 \%$ ) (allowable voltage range: $10.2 \ldots 28.8 \mathrm{~V} \mathrm{DC}$ ) |  |
|  | Current | 9 mA (at $24 \mathrm{~V} \mathrm{DC)/common}$ | 20 mA (at $24 \mathrm{~V} \mathrm{DC)/common}$ |
| Module size allocation |  | 1 |  |
| Number of occupied I/O points |  | 32 points (I/O assignment: input/output 32 points) |  |
| External interface |  | 40 -pin connector $\times 2$ |  |
| 5 V DC internal current consumption |  | 160 mA (TYP. all points ON) | 150 mA (TYP. all points ON) |
| Weight |  | 0.12 kg |  |

## - How to read the product code



Multiple Input (Voltage/Current/Temperature) Module

## Analog Input Modules



## Analog Output Module



## Analog I/O Module

Temperature Input Module


## L60RD8

Number of inputs: 8 channels
Input RTD: Pt1000, Pt100 (JIS C 1604-2013), JPt100 (JIS C 1604-1981), PP50 (JIS C 1604-1981),
Ni500 (DIN 43760 1987), Ni120 (DIN 43760 1987), Ni100 (DIN 43760 1987),
Cu100 (GOST 6651-2009, $\alpha=0.00428$ ), Cu50 (GOST 6651-2009, $\alpha=0.00428$ )
Conversion speed: $40 \mathrm{~ms} / \mathrm{ch}$
Resolution: $0.1^{\circ} \mathrm{C}$

■ Multiple/analog/temperature input features

| Function |  |  | Multiple input (voltage/current/ temperature) module | Analog input module |  |  |  | Analog I/O module | Temperature input module |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | L60MD4-G | L60AD4 | L60ADVL8 | L60ADIL8 | L60AD4-2GH | L60AD2DA2 | L60RD8 |
| Channel isolation |  |  | - | - | - | - | - ${ }^{1}$ | - | - |
| AD conversion method | Sampling processing |  | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | - |
|  | Averaging processing | Time average | - | - | - | - | - | - | $\bullet$ |
|  |  | Count average | - | - | - | - | - | - | - |
|  |  | Moving average | - | - | $\bullet$ | - | $\bullet$ | - | $\bullet$ |
| Time lag filter function |  |  | - | - | - | - | $\bullet$ | - | - |
| Digital filtering function |  |  | - | - | - | - | $\bullet$ | - | - |
| Conversion speed switch function |  |  | - | $\bullet$ | - | - | - | - | - |
| Input range extended mode function |  |  | - | ${ }^{*}{ }^{2}$ | - | $\bullet$ | - | $\bullet$ | - |
| Maximum value/minimum value hold function |  |  | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |
| Disconnection detection function |  |  | $\bullet$ | - | - | - | - | - | $\bullet$ |
| Input signal error detection function |  |  | $\bullet$ | $\bullet$ | - | $\bullet$ | $\bullet$ | $\bullet$ | - |
| Input signal error detection extension function |  |  | - | ${ }^{2}{ }^{2}$ | $\bullet$ | $\bullet$ | - | - | - |
| Warning output function | Process alarm |  | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | - | $\bullet$ |
|  | Rate alarm |  | - | - | - | - | - | - | $\bullet$ |
| Scaling function |  |  | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |
| 2-point sensor compensation function |  |  | - | - | - | - | - | - | $\bullet$ |
| Shift function |  |  | - ${ }^{3}$ | ${ }^{+2}$ | - ${ }^{3}$ | - ${ }^{3}$ | $\bullet$ | - ${ }^{3}$ | $\bullet$ |
| Digital clipping function |  |  | - ${ }^{3}$ | $\bullet$ | - ${ }^{3}$ | - ${ }^{3}$ | $\bullet$ | - ${ }^{3}$ | - |
| Difference conversion function |  |  | - ${ }^{3}$ | $\bullet^{2}$ | - ${ }^{3}$ | - ${ }^{3}$ | $\bullet$ | - ${ }^{3}$ | - |
| Logging function |  |  | - ${ }^{4}$ | $\bullet^{2}$ | - ${ }^{4}$ | - ${ }^{4}$ | $\bullet$ | $\bullet$ | - ${ }^{4}$ |
| Flow amount integration function |  |  | - | $\bullet^{2}$ | - | - | - | - | - |
| Trigger conversion function |  |  | - | - | - | - | $\bullet$ | - | - |
| Variable arithmetic function |  |  | - | - | - | - | - | ${ }^{\text {- }}$ | - |
| Variable conversion characteristics function |  |  | - | - | - | - | - | ${ }^{\text {- }}$ | - |
| Variable conversion characteristics function + variable arithmetic function |  |  | - | - | - | - | - | ${ }^{*}{ }^{5}$ | - |

■ Analog output features

| Function |  | Analog output module | Analog I/O module |
| :---: | :---: | :---: | :---: |
|  |  | L60DA4 | L60AD2DA2 |
| Analog output HOLD/CLEAR function |  | - | $\bullet$ |
| Scaling function |  | $\bullet$ | $\bullet$ |
| Warning output function | Process alarm | - | - |
| Wave output function |  | ${ }^{*}{ }^{6}$ | - |
|  | Wave output step action function | - ${ }^{6}$ | $\bullet$ |
| Variable arithmetic function |  | - | - ${ }^{\text {5 }}$ |
| Variable conversion characteristics function |  | - | - ${ }^{5}$ |
| Variable conversion characteristics function + variable arithmetic function |  | - | - ${ }^{5}$ |

${ }^{*} 1$ : Every two channels are isolated. ( CH 1 and CH 2 are isolated from CH 3 and CH 4 ).
*2: Supported by models whose first five serial number digits are "13041" or later.
*3: Please use function blocks (FB) for the shift function, digital clipping function, and difference conversion function. The function blocks (FB) can be downloaded for free from the MELSOFT Library on the Mitsubishi Electric FA site.
*4: For logging, please use the data logging function of the CPU module.
*5: Supported by models whose first five serial number digits are "17042" or later.
*6: Supported by models whose first five serial number digits are "14041" or later.

## Analog/Temperature Control

## Easily and finely adjust the system startup time with the shift function

## Shift function

Using this function, the set shifting amount to conversion value can be added (shifted) to the digital output value.
When the shifting amount to conversion value is changed, it is reflected to the scaling value (digital operation value) in real time. Therefore, fine adjustment can be easily performed when the system starts.

For L60AD4

| Before adjustment |  |  |
| :---: | :---: | :---: |
| Input voltage (V) | Digital output value |  |
| 0 | -10 |  |
| 5 | 19990 |  |
| Shifting amount to <br> conversion value: +10 |  |  |
| After adjustment | Scaling value <br> Input voltage (V) <br> (digital operation value) |  |
| 0 | 0 |  |
| 5 | 20000 |  |



Reduce the time taken for programming

## Scaling function

The scaling function converts values directly to easy-to-understand units without requiring any programming. Since a separate conversion program is not required, the number of overall programming steps can be reduced.
Scaling settings example (L60AD4)
Normally an analog input of 4 to 20 mA is converted to a digital value from 0 to 20000 . Using the scaling feature, the same input can result in a digital value of $\pm 20000$.


| Input current (mA) | Digital output value | Scaling value |
| :---: | :---: | :---: |
| 4 | 0 | -20000 |
| 8 | 5000 | -10000 |
| 12 | 10000 | 0 |
| 16 | 15000 | 10000 |
| 20 | 20000 | 20000 |

## Digital filtering function

This function eliminates unnecessary frequency elements with simple parameter settings. Select from low pass filter, high pass filter or band pass filter.
Programming steps can be further reduced as extra ladder code is not required to achieve the filter processing.
The filtered A/D conversion program is available at the same time as conversion completion, reducing the overall conversion to filter process time.


## First-delay filter function

The first-delay filter function constant outputs a digital value which filters out (smooths) the excessive noise.

## Log data for up to $\mathbf{1 0 , 0 0 0}$ points

## Logging function

Data is continuously collected at the set cycle and stored in the buffer memory.
Data stored in the buffer memory can be used for debugging, and to periodically confirm data variations.

The logging data can be analyzed with the GX LogViewer.

| Item | Description |  |  |
| :---: | :---: | :---: | :---: |
|  | L60AD4 | L60AD4-2GH | L60AD2DA2 |
| Collectable points | 10000 points/channel |  |  |
| Collectable data | Digital output value or scaling value (digital operation value) |  |  |
| Logging cycle*1 | $80 \ldots 32767 \mu \mathrm{~s}$ <br> $1 . . .32767 \mathrm{~ms}$ <br> $1 . .3600 \mathrm{~s}$ | $40 . . .32767 \mu \mathrm{~s}$ <br> $1 . . .32767 \mathrm{~ms}$ <br> $1 . . .3600$ s | 80... $32767 \mu \mathrm{~s}$ <br> 1... 32767 ms <br> $1 . .3600 \mathrm{~s}$ |
| Conversion speed | $80 \mu \mathrm{~s}$, or 1 ms | $40 \mu \mathrm{~s} / 2$ channels | $80 \mu \mathrm{~s}$ |
| Level trigger condition | Above, Below, Pass Through |  |  |
| Logging points after trigger | 1... 10000 |  |  |
| *1: The actual logging cycle is "an integral multiple of the conversion cycle of each A/D conversion method". <br> Ex.) When using the sampling processing: Conversion cycle = conversion speed $\times$ number of channels in use. |  |  |  |



Logging data can be transferred to the CPU device memory while still logging.
Logging and data transmission can be executed simultaneously so the next logging session can be started right away.

## Logging for 10,000 points and greater

When logging of 1001-2000 points of data commences, the first 1000 points (1-1000) are stored into the CPU device memory. By storing every 1000 points of data in the CPU, overall logging of total data larger than 1000 points can be logged.


Easily measure part thicknesses!

## Difference conversion function

When the difference conversion starts, the scaling value (digital operation value) at that time is determined as the difference conversion reference value. The value acquired by subtracting the difference conversion reference value from the scaling value (digital operation value) is stored as the scaling value (digital operation value) after difference conversion.

## Extend the detection method according to applications

Input signal error detection extension function
Using this function, the detection method of the input signal error detection function can be extended. Use this function to detect an input signal error only at the lower or upper limit, or to execute the disconnection detection.

## Input range extension function

The input range can be extended. By combining this function with the input signal error detection function, simple disconnection detection can be executed.

## Connected devices monitoring alarm

## Warning output function

- Process alarm

Outputs an alarm when the digital output value enters a preset alarm range.


Rate alarm
An alarm is generated if the digital output value's variation rate is larger than the rate alarm upper limit value, or if it is smaller than the rate alarm lower limit value.


Noise isolation for smoother system operation

## Channel isolation

Each channel is isolated preventing any noise interference between channels resulting in more stable measurements.


## A/D variable conversion timing

## Trigger conversion function

A/D conversion is processed at the rising edge of the trigger position timing.
This function enables easier use of the converter and enhances the overall program performance.
There are two types of trigger conversion request:
"External trigger conversion request (external input terminal)" or "internal trigger conversion request (buffer memory)".

*1: Carried out in order with combination of channel 1, channel 3 and channel 2, channel 4 .


| Item | Description |  |  |
| :---: | :---: | :---: | :---: |
| Integrated flow amount | Result of integral processing |  |  |
| Instantaneous flow amount | Instantaneous flow amount value output in analog from flow meter |  |  |
| $\Delta \mathrm{T}$ | Integration cycle (ms) |  |  |
| T | Conversion value to convert time unit of instantaneous flow amount to ms unit |  |  |
|  | Range of flow meter | Setting value to specify flow amount time unit | T (ms) |
|  | /s | 0 | 1000 |
|  | /min | 1 | 60000 |
|  | /h | 2 | 3600000 |
| Unit scaling | Unit scaling for integrated flow amount This is used when the value of instantaneous flow amount $\times \Delta \mathrm{T} / \mathrm{T}$ is 0 to 1 . |  |  |
|  |  | value to specify unit scaling | Unit scaling |
|  |  | 0 | 1 |
|  |  | 1 | 10 |
|  |  | 2 | 100 |
|  |  | 3 | 1000 |
|  |  | 4 | 10000 |
| Previous amount | Stored integrated flow amount value before integral processing |  |  |

## Analog/Temperature Control

## Realize fast and smooth continuous analog output

## Wave output function

The industry's first ${ }^{41}$ waveform output function is included.
This function enables control wave data that is faster than the program control to be directly registered in the D/A converter module and output the data at a set conversion cycle.
Therefore, the analog output value is not affected by the scan time of the CPU module resulting in faster and smoother analog control.
*1: Mitsubishi Electric survey dated April 2012.
Analog output from sequence program
Analog values are output at each scan time

Analog output with waveform output function
Analog values are output at set interval.


The actual waveform and the output waveform deviate.


The output waveform is closer to the actual waveform (less deviation).
(1) Using GX Works2 to create the waveform output data to be analog output


By registering the waveform patterns (multiple), they can be combined freely with the tool.
(2) Save waveform output data into CPU module's file resister (or SD memory card)


Save waveform output data onto SD memory card in situations with no access to a PC
(3) Execute the function block (FB) ${ }^{\star 2}$ and register into analog output module


Register to analog output module (analog input/output module) buffer memory

## More flexible calculation and conversion reduce programming time

## Conversion by polynomial expressions

The variable arithmetic function enables the analog I/O module to perform polynomial calculations, eliminating the need of such calculations programmed by ladder. With the calculations performed on the analog I/O module side, advanced calculations are possible without being restricted by the scan time.


## Graph-form conversion characteristics

The variable conversion characteristics function enables conversion characteristics for analog input, analog output, and analog I/O to be easily set on graphs. This means that conversion characteristics do not need to be programmed by ladder, which leads to reduced programming time.

| Item | Description |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Analog input | Conversion characteristics can be easily set for the A-D conversion channels (CH1, CH2). |  |  |  |
| Analog output | Conversion characteristics can be easily set for the D-A conversion channels ( $\mathrm{CH} 3, \mathrm{CH} 4$ ). |  |  |  |
| Analog I/O | Conversion characteristics for the analog input-output conversion can be easily set in simple steps, eliminating the need of creating ladder programs. |  |  |  |
| Previous control method |  | Control using graph-form conversion characteristics |  |  |
| Ex.) Analog output module |  | Ex.) Analog I/O module |  |  |
| Analog output value (V) <br> 10 [ |  | Analog output value (V) |  |  |
| $-10 \bigsqcup_{-16}$ |  | $-10$ | 0 | 10 |
|  | Digital input value |  |  | Analog input value (V) |
| Straight line between the offset and gain values was the conversion characteristics |  | Conversion characteristics can be easily set |  |  |

## Conversion by graph-form conversion characteristics plus polynomial expressions

The two functions described above can also be combined; the digital values are first converted according to graph-form conversion characteristics and then by polynomial expressions. These two levels of conversion realize full adjustment of analog values at the time of output rather than adjusting them post-conversion.

Ex.) Obtaining intended analog output using the conversion by graph-form conversion characteristics plus polynomial expressions


One module covering voltage, current, micro-voltage, thermocouples and RTD
For each channel, it is possible to select from voltage, current, micro-voltage, thermocouples or RTD. As a result, dedicated modules required for each type of sensor can now be integrated into a single module.


The multiple input module also supports the Pt50 and JPt100 sensors, which are compatible with the former JIS standards. Modules can be replaced without altering the already existing sensor equipment.

| Thermocouple | K, J, T, E, N, R, S, B, U, L, PL II, W5Re/W26Re |
| :--- | :--- |
| RTD | Pt1000, Pt100, JPt100, Pt50 |

## 8 input channels with wider input ranges

Single L60RD8 can measure temperatures of up to 8 channels. With the number of supported channels doubled compared to before (L60MD4-G), space and cost savings can be realized. The input range is expanded to meet the DIN standards, GOST standards, and Pt1000 range in addition to Pt100, JPt100, and Pt50, bringing new application possibilities.

| RTD | Pt1000, Pt100, JPt100, Pt50, Ni (DIN standards), Cu (GOST standards) |
| :--- | :--- |

## Reduced wiring time with no screw tightening

L60RD8
The module is equipped with a spring clamp terminal block, which does not require screw tightening. This push-in type terminal block does not require any dedicated wiring tool and significantly reduces the installation time.


## Easier calibration

 L60RD8Measured temperatures can be easily calibrated towards the actual temperature using the sensor calibration function (shift function, 2-point sensor compensation function).


The measured temperature of $\mathbf{1 0 . 8}$ to $50.7\left({ }^{\circ} \mathrm{C}\right)$ is calibrated to be 10.5 to $50.0\left({ }^{\circ} \mathrm{C}\right)$ by digital calculation. A temperature closer to the one input to RTD is obtained.

■ Multiple input (voltage/current/temperature) module specifications

| Item |  | L60MD4-G |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Number of analog input channels |  | 4 channels |  |  |  |  |  |
| Analog input | Voltage | $-10 \ldots 10 \mathrm{~V}$ DC ( Input resistance value $1 \mathrm{M} \Omega$ ) |  |  |  |  |  |
|  | Current | $0 . . .20 \mathrm{~mA} \mathrm{DC}$ ( Input resistance value $250 \Omega$ ) |  |  |  |  |  |
|  | micro voltage | -100... 100 mV DC |  |  |  |  |  |
|  | Thermocouple | Available type |  |  | K, J, T, E, N, R, S, B, U, L, PL II, W5Re/W26Re |  |  |
|  |  | Cold junction compensation resistor |  |  | Use the included cold junction compensation resistor (CJ) |  |  |
|  | Resistive thermal device | Available type |  |  | Pt1000, Pt100, JPt100, Pt50 |  |  |
|  |  | Measurement method |  |  | 3 -wire system |  |  |
| Digital output |  | Voltage, Current, micro voltage |  |  | -20480... 20479 |  |  |
|  |  | Resistive thermal device Pt100 (-20...120 ${ }^{\circ} \mathrm{C}$ ), JPt100 ( $-20 \ldots 120^{\circ} \mathrm{C}$ ) |  |  | $-2000 \ldots 20000$ : Value rounded off to two decimal places $\times 100$ times |  |  |
|  |  | Thermocouple, Resistive thermal device (other than the above) |  |  | $-4000 \ldots . .32000$ : Value rounded off to one decimal place $\times 10$ times |  |  |
|  | When using the scaling function | -32768...32767 |  |  |  |  |  |
| I/O characteristics, resolution |  | Analog input range |  | Digital output value |  | Resolution |  |
|  |  | $0 . . .10 \mathrm{~V}$ |  | 0... 20000 |  | $500 \mu \mathrm{~V}$ |  |
|  |  | Voltage |  | 0... 20000 |  | $250 \mu \mathrm{~V}$ |  |
|  |  |  | 0...20000 |  | $200 \mu \mathrm{~V}$ |  |
|  |  | 10 V | -20000...20000 |  | $500 \mu \mathrm{~V}$ |  |
|  |  | $1 . .5 \mathrm{~V}$ (Extended mode) | -5000...22500 |  | $200 \mu \mathrm{~V}$ |  |
|  |  | Current | $0 . . .20 \mathrm{~mA}$ | 0... 20000 |  | 1000 nA |  |
|  |  | mA | 800 nA |  |
|  |  | 4...20 mA (Extended mode) | -5000... 22500 |  | 800 nA |  |
|  |  | micro voltage - $100 \ldots 100 \mathrm{mV}$ | -20000...20000 |  | $5 \mu \mathrm{~V}$ |  |
|  |  | Thermocouple | $\begin{gathered} \text { B, R, S, N, PL II, W5Re/W26Re: } 0.3^{\circ} \mathrm{C} \\ \text { K, E, J, T, U, L: } 0.1^{\circ} \mathrm{C} \end{gathered}$ |  |  |  |
|  |  | Resistive thermal device (RTD) | Pt100 (-20...120 ${ }^{\circ} \mathrm{C}$ ), <br> JPt100 (-20...120 $\left.{ }^{\circ} \mathrm{C}\right): 0.03^{\circ} \mathrm{C}$ Pt100 (-200... $850^{\circ} \mathrm{C}$ ), <br> JPt100 (-200... $\left.600^{\circ} \mathrm{C}\right)$, Pt1000, Pt50: $0.1^{\circ} \mathrm{C}$ |  |  |  |
| Accuracy ${ }^{1+2}$ |  |  | Voltage/Current/ micro voltage |  |  | Ambient temperature $25 \pm 5^{\circ} \mathrm{C}$ |  | Maximum value of the measurement rangex $( \pm 0.3 \%$ ) |  |  |
|  |  | Ambient temperature $0 \ldots . .55^{\circ} \mathrm{C}$ |  | Maximum value of the measurement rangex $( \pm 0.9 \%$ ) |  |  |
|  |  | Thermocouple | Ambient temperature $25 \pm 5^{\circ} \mathrm{C}$ |  | Full scale $\times( \pm 0.15 \%)$ |  |  |
|  |  | Ambient temperature $0 . \ldots 55^{\circ} \mathrm{C}$ | Full scale $\times( \pm 0.3 \%)^{3}$ |  |  |
|  |  | Cold junction compensation resistor ${ }^{4}$ | Temperature measured value: $-100^{\circ} \mathrm{C}$ or higher |  | $\leq \pm 1.0^{\circ} \mathrm{C}$ |  |  |
|  |  | Temperature measured value:$-150^{\circ} \mathrm{C} \ldots-100^{\circ} \mathrm{C}$ | $\leq \pm 2.0^{\circ} \mathrm{C}$ |  |  |
|  |  | Temperature measured value:$-200^{\circ} \mathrm{C} \ldots-150^{\circ} \mathrm{C}$ | $\leq \pm 3.0^{\circ} \mathrm{C}$ |  |  |
|  |  | Resistive thermal device | (Accuracy $)^{5}=($ Conversion accuracy $)+($ Temperature characteristics $) \times$ <br> (Operating ambient temperature change) <br> + (Allowable difference of resistance temperature detector used) |  |  |  |  |
| Conversion speed |  |  | $50 \mathrm{~ms} / \mathrm{ch}$ |  |  |  |  |  |
| Output current for temperature detection |  |  | Pt100, JPt100, Pt50: 1 mA, Pt1000: 0.2 mA |  |  |  |  |  |
| Absolute maximum input |  | Voltage: $\pm 15 \mathrm{~V}$, Current: $30 \mathrm{~mA}^{\text {/6 }}$ |  |  |  |  |  |
| Isolation method |  | Between I/O terminals and programmable controller power supply: photocoupler isolation Between input channels: transformer isolation |  |  |  |  |  |
| Module size allocation |  | 1 |  |  |  |  |  |
| Number of occupied I/O points |  | 16 points (//O assignment: 16 points for inteligent) |  |  |  |  |  |
| External interface |  | 18-point terminal block |  |  |  |  |  |
| 5 V DC internal current consumption |  | 0.49 A |  |  |  |  |  |
| Weight |  | 0.19 kg |  |  |  |  |  |

*1: Except when influenced by noise.
*2: To acquire sufficient accuracy, a warm-up (conduction) for 15 minutes is required.
*3: The accuracy for when the measured temperature of the type W5Re/W26Re thermocouple is $2000^{\circ} \mathrm{C}$ or higher is $\pm 0.5 \%$.
*4: The following table shows the accuracy of the cold junction compensation for when the type "T" thermocouple or type "U" thermocouple is used

| Measured temperature | T Thermocouple | U Thermocouple |
| :--- | :--- | :---: |
| $0^{\circ} \mathrm{C}$ or higher | $\pm 1.0^{\circ} \mathrm{C}$ |  |
| $-100^{\circ} \mathrm{C} \ldots 0^{\circ} \mathrm{C}$ | $\pm 2.0^{\circ} \mathrm{C}$ |  |
| $-150^{\circ} \mathrm{C} \ldots-100^{\circ} \mathrm{C}$ | $\pm 3.0^{\circ} \mathrm{C}$ | $\pm 4.0^{\circ} \mathrm{C}$ |
| $-200^{\circ} \mathrm{C} \ldots-150^{\circ} \mathrm{C}$ | $\pm 5.0^{\circ} \mathrm{C}$ |  |

*5: The following table shows RTD types and values for each item.

| RTD type | Celsius |  |  | Fahrenheit |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Measured temperature range | Conversion accuracy (operating ambient temperature: $25 \pm 5^{\circ} \mathrm{C}$ ) | Temperature characteristics (for a change of $1^{\circ} \mathrm{C}$ in the operating ambient temperature) | Measured temperature range | Conversion accuracy (operating ambient temperature: $25 \pm 5^{\circ} \mathrm{C}$ ) | Temperature characteristics (for a change of $1^{\circ} \mathrm{C}$ in the operating ambient temperature) |
| Pt100 | -20...-120 ${ }^{\circ} \mathrm{C}$ | $1^{\circ} \mathrm{C}$ | $0.1{ }^{\circ} \mathrm{C}$ | $0 \ldots 200^{\circ} \mathrm{F}$ | $1^{\circ} \mathrm{F}$ | $0.1^{\circ} \mathrm{F}$ |
|  | -200...850 ${ }^{\circ} \mathrm{C}$ | $2^{\circ} \mathrm{C}$ | $0.2^{\circ} \mathrm{C}$ | $-300 . .1500^{\circ} \mathrm{F}$ | $3^{\circ} \mathrm{F}$ | $0.3^{\circ} \mathrm{F}$ |
| JPt100 | -20...-120 ${ }^{\circ} \mathrm{C}$ | $1^{\circ} \mathrm{C}$ | $0.1{ }^{\circ} \mathrm{C}$ | $0 \ldots 200^{\circ} \mathrm{F}$ | $1^{\circ} \mathrm{F}$ | $0^{0.1}{ }^{\circ} \mathrm{F}$ |
|  | -200...600 ${ }^{\circ} \mathrm{C}$ | $2^{\circ} \mathrm{C}$ | ${ }^{0.2}{ }^{\circ} \mathrm{C}$ | $-300 . .1100^{\circ} \mathrm{F}$ | $3^{\circ} \mathrm{F}$ | $0^{0.3}{ }^{\circ} \mathrm{F}$ |
| Pt1000 | $-200 . .850^{\circ} \mathrm{C}$ | $2^{\circ} \mathrm{C}$ | $0.2^{\circ} \mathrm{C}$ | $-300 . .1500^{\circ} \mathrm{F}$ | $3^{\circ} \mathrm{F}$ | $0^{0.3}{ }^{\circ} \mathrm{F}$ |
| Pt50 | -200...650 ${ }^{\circ} \mathrm{C}$ | $2^{\circ} \mathrm{C}$ | $0.2^{\circ} \mathrm{C}$ | -300...1200 ${ }^{\circ} \mathrm{F}$ | $3^{\circ} \mathrm{F}$ | $0.2^{\circ} \mathrm{F}$ |

- Allowable difference of Pt100 (JIS C 1604-1997, IEC 751 1983)
- Allowable difference of Pt100, allowable difference of Pt50 (JIS C 1604-1981)

| Class | Allowable difference |
| :--- | :--- |
| A | $\pm(0.15+0.002 \mathrm{It})^{\circ} \mathrm{C}$ |
| B | $\pm(0.3+0.005 \mathrm{tt})^{\circ} \mathrm{C}$ |


| Class | Allowable difference |
| :--- | :--- |
| 0.15 | $\pm(0.15+0.0015 \mathrm{tt})^{\circ} \mathrm{C}$ |
| 0.2 | $\pm(0.15+0.002 \mathrm{It})^{\circ} \mathrm{C}$ |
| 0.5 | $\pm(0.3+0.005 \mathrm{It})^{\circ} \mathrm{C}$ |

The allowable difference of Pt1000 is not provided in the JIS standard, and therefore is not described here. Please contact your Mitsubishi Electric or local sales representative for further details.
*6: A momentary current value which does not cause damage to internal resistors of the module, although the maximum continuous input current is 24 mA

## Analog input module specifications

## L60AD4



## L60ADVL8


*1: Maximum resolution in the user range setting.
*2: Accuracy for the maximum value of the digital output value. Except when influenced by noise.
*3: The default value is $80 \mu \mathrm{~s} /$ channel.
*4: The logging function can be used only in the middle speed ( $80 \mu \mathrm{~s} /$ channel) or low speed ( $1 \mathrm{~ms} /$ channel )
*4: The logging function can be used only in the middle speed ( $80 \mu \mathrm{~s} /$ channel) or low speed
*5: The flow amount integration function can be used only in the low speed ( $1 \mathrm{~ms} /$ channel $)$.
*5: The flow amount integration function can be used only in the low speed ( $1 \mathrm{~ms} / \mathrm{channel}$ ).

Dual channel isolation analog input module specifications

| Item |  |  | L60AD4-2GH |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Number of analog input channels |  |  | 4 channels |  |  |  |
| Analog input | Voltage |  | $-10 \ldots 10 \mathrm{~V}$ DC (Input resistance value $1 \mathrm{M} \Omega$ ) |  |  |  |
|  | Current |  | $0 \ldots . .20 \mathrm{~mA} \mathrm{DC} \mathrm{( } \mathrm{Input} \mathrm{resistance} \mathrm{value} 250 \Omega$ ) |  |  |  |
| Digital output |  |  | -32000...32000 |  |  |  |
|  | When using the scaling function |  | -32768...32767 |  |  |  |
| I/O characteristics, resolution |  |  |  | Analog input range | Digital output value | Resolution |
|  |  |  | Voltage | $0 . . .10 \mathrm{~V}$ | 0...32000 | $312.5 \mu \mathrm{~V}$ |
|  |  |  | $0 . .5 \mathrm{~V}$ | $156 \mu \mathrm{~V}$ |  |
|  |  |  | $1 \ldots .5 \mathrm{~V}$ | $125 \mu \mathrm{~V}$ |  |
|  |  |  | -10...10 V | -32000...32000 | $312.5 \mu \mathrm{~V}$ |
|  |  |  | $1 \ldots . .5 \mathrm{~V}$ (Extended mode) | -8000...32000 | $125 \mu \mathrm{~V}$ |
|  |  |  | Users range setting (Bipolar: voltage) | -32000...32000 | $200 \mu \mathrm{~V}^{*_{1}}$ |
|  |  |  | Current | $0 . . .20 \mathrm{~mA}$ | 0... 32000 | 625 nA |
|  |  |  | $4 . .20 \mathrm{~mA}$ | 500 nA |  |
|  |  |  | $4 \ldots . .20 \mathrm{~mA}$ (Extended mode) | -8000...32000 | 500 nA |
|  |  |  | Users range setting (Unipolar: Current) | $0 . .32000$ | $400 \mathrm{nA}^{*_{1}}$ |
| Accuracy*2 | Reference accuracy** |  |  | $\leq \pm 0.05 \%$ ( $\pm 16$ digit) |  |  |  |
|  | Temperature coefficient ${ }^{\text {t }}$ |  |  | $\leq \pm 40.1 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ |  |  |  |
| Conversion speed |  |  |  | $40 \mu \mathrm{~s} / 2$ channel |  |  |  |
| Absolute maximum input |  |  | Voltage: $\pm 15 \mathrm{~V}$, Current: $30 \mathrm{~mA}^{* 5}$ |  |  |  |
| Isolation method |  |  | etween I/O terminals and programmable controller power supply: photocoupler isolation Between analog input channels: dual channel transformer isolation |  |  |  |
| Module size allocation |  |  | 1 |  |  |  |
| Number of occupied I/O points |  |  | 16 points (//O assignment: 16 points for intelligent) |  |  |  |
| External interface |  |  | 18-point terminal block |  |  |  |
| 5 V DC internal current consumption |  |  | 0.76 A |  |  |  |
| Weight |  |  | 0.20 kg |  |  |  |
| External trigger input | Input points |  | 1 point |  |  |  |
|  | Rated input voltage |  | 24 V DC (+ 20\%/-15\%, ripple ratio: $\leq 5 \%$ ) |  |  |  |
|  | Rated input current |  | 6.0 mA TYP . (at 24 V DC) |  |  |  |
|  | ON voltage/ON current |  | $\geq 13 \mathrm{~V}, \geq 3 \mathrm{~mA}$ |  |  |  |
|  | OFF voltage/OFF current |  | $\leq 8 \mathrm{~V}, \leq 1.6 \mathrm{~mA}$ |  |  |  |
|  | Input resistance |  | $3.9 \mathrm{k} \Omega$ |  |  |  |
|  | Response | OFF to ON | $40 \mu \mathrm{~s}$ |  |  |  |
|  | time | ON to OFF | $40 \mu \mathrm{~s}$ |  |  |  |

1: Maximum resolution in the user range setting.
*2: Accuracy for the maximum value of the digital output value. Except when influenced by noise.
*3: Accuracy under the ambient temperature when the offset/gain setting is performed.
*4: Accuracy when the temperature changes $1^{\circ} \mathrm{C}$.
Example: Accuracy when the temperature changes from $25^{\circ} \mathrm{C}$ to $30^{\circ} \mathrm{C}$
$0.05 \%+0.00401 \% /{ }^{\circ} \mathrm{C}$ (temperature coefficient) $\times 5^{\circ} \mathrm{C}$ (temperature change) $=0.070 \%$
*5: A momentary input current value which does not cause damage to internal resistors of the module. The maximum input current value for constant application is 24 mA .
■ Analog output module specifications

| Item <br> Number of analog output channels |  | L60DA4 |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  |
| Digital input |  | -20480... 20479 |  |  |  |
| When using the scaling function |  | -32768... 32767 |  |  |  |
| Analog output | Voltage | $-10 \ldots 10 \mathrm{~V}$ DC (External load resistance value $1 \mathrm{k} \Omega . .1 \mathrm{M} \Omega$ ) |  |  |  |
|  | Current | $0 . . .20 \mathrm{~mA} \mathrm{DC} \mathrm{(External} \mathrm{load} \mathrm{resistance} \mathrm{value} 0 \Omega \ldots 600 \Omega$ ) |  |  |  |
| I/O characteristics, resolution |  |  | og output range | Digital value | Resolution |
|  |  | Voltage | $0 . . .5 \mathrm{~V}$ | 0... 20000 | $250 \mu \mathrm{~V}$ |
|  |  | $1 . . .5 \mathrm{~V}$ | $200 \mu \mathrm{~V}$ |  |
|  |  | -10... 10 V | -20000... 20000 | $500 \mu \mathrm{~V}$ |
|  |  | Users range setting |  | $333 \mu \mathrm{~V}^{*}{ }_{6}$ |
|  |  | Current | $0 . . .20 \mathrm{~mA}$ | 0... 20000 | 1000 nA |
|  |  | 4... 20 mA | 800 nA |  |
|  |  | Users range setting | -20000... 20000 | $700 \mathrm{nA}{ }^{*}{ }_{6}$ |
| Accuracy ${ }^{7}$ | Ambient temperature $25 \pm 5^{\circ} \mathrm{C}$ |  | $\leq \pm 0.1 \%$ |  |  |  |
|  | Ambient temperature $0 . . .55^{\circ} \mathrm{C}$ |  | $\leq \pm 0.3 \%$ |  |  |  |
| Conversion speed | Normal output mode | $20 \mu \mathrm{~s} /$ channel |  |  |  |
|  | Wave output mode | $50 \mu \mathrm{~s} /$ channel $80 \mu \mathrm{~s} /$ channel |  |  |  |
| Output short protection |  | Protected |  |  |  |
| Isolation method |  | tween I/O terminals and programmable controller power supply: photocoupler isolation Between output channels: no isolation <br> Between external power supply and analog output: transformer isolation |  |  |  |
| Module size allocation |  | 1 |  |  |  |
| Number of occupied I/O points |  | 16 points (1/O assignment: 16 points for intelligent) |  |  |  |
| External interface |  | 18-point terminal block |  |  |  |
| External power supply |  | 24 V DC (+ 20\%/-15\%) |  |  |  |
|  |  | Ripple, spike 500 mV P-p or lower |  |  |  |
|  |  | Inrush current: $4.3 \mathrm{~A}, 1000 \mu \mathrm{~s}$ or shorter |  |  |  |
|  |  | Current consumption: 0.18 A |  |  |  |
| 5 V DC internal current consumption |  | 0.16 A |  |  |  |
| Weight |  | 0.20 kg |  |  |  |
| *7: Accuracy for the maximum value of analog output value. Except when influenced by noise. Warm up (power on) the module for 30 minutes to satisfy the accuracy shown in the table. |  |  |  |  |  |

■ Analog input/output module specifications


## *1: Maximum resolution in the user range setting.

*2: Accuracy for the maximum value of the digital /analog output value. Except when influenced by noise
*3: A momentary current value which does not cause damage to internal resistors of the module, although the maximum continuous input current 24 mA .
*4: When the variable arithmetic function or the variable conversion characteristics function + variable arithmetic function is used, the operation speed for polynomial expressions is $320 \mu \mathrm{~s}$. Since each operation result of two polynomial expressions is output on each D/A conversion channel, D/A conversion is executed at intervals of $320 \mu \mathrm{~s}$ regardless of the number of conversion enabled channels.

- Temperature input module specifications

*1: The following table shows RTD types and values for each item.

| RTD type | Celsius |  |  | Fahrenheit |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Measured temperature range | Conversion accuracy |  | Measured temperature range | Conversion accuracy |  |
|  |  | Operating ambient temperature $25 \pm 5^{\circ} \mathrm{C}$ | Operating ambient temperature $0 . .55^{\circ} \mathrm{C}$ |  | Operating ambient temperature $25 \pm 5^{\circ} \mathrm{C}$ | Operating ambient temperature $0 \ldots . .55^{\circ} \mathrm{C}$ |
| Pt100 | $-20 . . .120^{\circ} \mathrm{C}$ | $\pm 0.6^{\circ} \mathrm{C}$ | $\pm 2.0^{\circ} \mathrm{C}$ | $-4 . . .248^{\circ} \mathrm{F}$ | $\pm 1.1^{\circ} \mathrm{F}$ | $\pm 3.6{ }^{\circ} \mathrm{F}$ |
|  | $-200 . . .850^{\circ} \mathrm{C}$ | Specified temperature $\times \pm 0.3 \%$ or $\pm 0.8^{\circ} \mathrm{C}$, whichever is greater | Specified temperature $\times \pm 0.8 \%$ or $\pm 2.7^{\circ} \mathrm{C}$, whichever is greater | -328...1562 ${ }^{\circ} \mathrm{F}$ | Specified temperature $x \pm 0.3 \%$ or <br> $\pm 1.5^{\circ} \mathrm{F}$, whichever is greater | Specified temperature $\times \pm 0.8 \%$ or $\pm 4.9^{\circ} \mathrm{F}$, whichever is greater |
| JPt100 | $-20 . .120^{\circ} \mathrm{C}$ | $\pm 0.6^{\circ} \mathrm{C}$ | $\pm 2.0^{\circ} \mathrm{C}$ | $-4 . . .248^{\circ} \mathrm{F}$ | $\pm 1.1^{\circ} \mathrm{F}$ | $\pm 3.6^{\circ} \mathrm{F}$ |
|  | $-200 . .600^{\circ} \mathrm{C}$ | Specified temperature $\times \pm 0.3 \%$ or $\pm 0.8^{\circ} \mathrm{C}$, whichever is greater | Specified temperature $\times \pm 0.8 \%$ or $\pm 2.7^{\circ} \mathrm{C}$, whichever is greater | -328...1112 ${ }^{\circ} \mathrm{F}$ | Specified temperature $x \pm 0.3 \%$ or $\pm 1.5^{\circ} \mathrm{F}$, whichever is greater | Specified temperature $\times \pm 0.8 \%$ or $\pm 4.9^{\circ} \mathrm{F}$, whichever is greater |
| Pt1000 | $-200 . .850^{\circ} \mathrm{C}$ | Specified temperature $\times \pm 0.3 \%$ or $\pm 0.8^{\circ} \mathrm{C}$, whichever is greater | Specified temperature $x \pm 0.8 \%$ or $\pm 2.7^{\circ} \mathrm{C}$, whichever is greater | $-328 . .1562^{\circ} \mathrm{F}$ | Specified temperature $x \pm 0.3 \%$ or $\pm 1.5^{\circ} \mathrm{F}$, whichever is greater | Specified temperature $\times \pm 0.8 \%$ or $\pm 4.9^{\circ} \mathrm{F}$, whichever is greater |
| Pt50 | $-200 . .650^{\circ} \mathrm{C}$ | Specified temperature $\times \pm 0.3 \%$ or $\pm 0.8^{\circ} \mathrm{C}$, whichever is greater | Specified temperature $x \pm 0.8 \%$ or $\pm 4.1^{\circ} \mathrm{C}$, whichever is greater | $-328 . .1202^{\circ} \mathrm{F}$ | Specified temperature $\times \pm 0.3 \%$ or $\pm 1.5^{\circ} \mathrm{F}$, whichever is greater | Specified temperature $\times \pm 0.8 \%$ or $\pm 7.4^{\circ} \mathrm{F}$, whichever is greater |
| Ni100 | $-60 . .250^{\circ} \mathrm{C}$ | $\pm 0.6^{\circ} \mathrm{C}$ | Specified temperature $\times \pm 0.8 \%$ or $\pm 1.4^{\circ} \mathrm{C}$, whichever is greater | -76...482 ${ }^{\circ} \mathrm{F}$ | $\pm 1.1^{\circ} \mathrm{F}$ | Specified temperature $\times \pm 0.8 \%$ or $\pm 2.6^{\circ} \mathrm{F}$, whichever is greater |
| Ni120 | $-60 . .250^{\circ} \mathrm{C}$ | $\pm 0.6^{\circ} \mathrm{C}$ | Specified temperature $x \pm 0.8 \%$ or $\pm 1.4^{\circ} \mathrm{C}$, whichever is greater | -76...482 ${ }^{\circ} \mathrm{F}$ | $\pm 1.1{ }^{\circ} \mathrm{F}$ | Specified temperature $\times \pm 0.8 \%$ or $\pm 2.6^{\circ} \mathrm{F}$, whichever is greater |
| Ni500 | $-60 . .250^{\circ} \mathrm{C}$ | $\pm 0.6^{\circ} \mathrm{C}$ | Specified temperature $\times \pm 0.8 \%$ or $\pm 1.4^{\circ} \mathrm{C}$, whichever is greater | $-76 . .482^{\circ} \mathrm{F}$ | $\pm 1.1^{\circ} \mathrm{F}$ | Specified temperature $\times \pm 0.8 \%$ or $\pm 2.6^{\circ} \mathrm{F}$, whichever is greater |
| Cu100 | $-180 . . .200^{\circ} \mathrm{C}$ | $\pm 0.8^{\circ} \mathrm{C}$ | $\pm 2.7^{\circ} \mathrm{C}$ | -292...392 ${ }^{\circ} \mathrm{F}$ | $\pm 1.5^{\circ} \mathrm{F}$ | $\pm 4.9^{\circ} \mathrm{F}$ |
| Cu50 | $-180 . . .200^{\circ} \mathrm{C}$ | $\pm 0.8^{\circ} \mathrm{C}$ | $\pm 2.7^{\circ} \mathrm{C}$ | -292...392 ${ }^{\circ} \mathrm{F}$ | $\pm 1.5^{\circ} \mathrm{F}$ | $\pm 4.9^{\circ} \mathrm{F}$ |

- Allowable difference of Pt100 (JIS C 1604-2013) - Allowable difference of JPt100 and Pt50 (JIS C 1604-1981)

| Class | Allowable difference |
| :--- | :--- |
| A | $\pm\left(0.15+0.002 i^{\prime} t\right)^{\circ} \mathrm{C}$ |
| B | $\pm\left(0.3+0.005 t^{\prime}\right)^{\circ} \mathrm{C}$ |


| Class | Allowable difference |
| :--- | :--- |
| 0.15 | $\pm\left(0.15+0.0015 \text { 't }^{\prime}\right)^{\circ} \mathrm{C}$ |
| 0.2 | $\pm\left(0.15+0.002 \mathrm{t}^{\circ}\right)^{\circ} \mathrm{C}$ |
| 0.5 | $\pm\left(0.3+0.005\left(\mathrm{t}^{\prime}\right)^{\circ} \mathrm{C}\right.$ |

- Allowable difference of Ni100, Ni120, and Ni500 (DIN 43760 1987)

| Class | Allowable difference |
| :--- | :--- |
| $-60 \ldots 0^{\circ} \mathrm{C}$ | $\pm\left(0.4+0.007 \mathrm{t}^{\prime}\right)^{\circ} \mathrm{C}$ |
| $0 \ldots 250^{\circ} \mathrm{C}$ | $\pm\left(0.3+0.0028 \mathrm{t}^{\prime}\right)^{\circ} \mathrm{C}$ |

- Allowable difference of Cu100 and Cu50 (GOST 6651-2009)

| Class | Allowable difference |
| :---: | :---: |
| AA | $\left.\pm\left(0.1+0.0017 \mathrm{t}^{\prime}\right)^{\prime}\right)^{\circ} \mathrm{C}$ |
| A | $\left.\pm\left(0.15+0.002 i^{\prime}\right)^{\prime}\right)^{\circ} \mathrm{C}$ |
| B | $\pm(0.3+0.005 . \mathrm{t} \text { ') })^{\circ} \mathrm{C}$ |
| C | $\pm\left(0.6+0.01 \text { it } t^{\prime}\right)^{\circ} \mathrm{C}$ |

The allowable difference of Pt1000 is not provided in the JIS standard, and therefore is not described here.
Please contact your Mitsubishi Electric or local sales representative for further details.
*2: Current is output only on channels in which conversion is being performed.
*3: When the standard product (L60MD4-G) is replaced by this module, the resolution of $\mathrm{Pt} 100\left(-20\right.$ to $120^{\circ} \mathrm{C}$ ) and $\mathrm{JPt100}\left(-20 \mathrm{to} 120^{\circ} \mathrm{C}\right.$ ) is different.
*4: When a stranded wire is used, attach a bar solderless terminal.

## Temperature Control Modules



| Function | L60TCTT4 | L60TCTT4BW | L60TCRT4 | L60TCRT4BW |
| :---: | :---: | :---: | :---: | :---: |
|  | Thermocouple input |  | RTD input |  |
| Standard control | $\bullet$ | - | $\bullet$ | $\bullet$ |
| Heating-cooling control | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |
| Self-tuning function | $\bullet$ | - | $\bullet$ | - |
| Peak current suppression function | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |
| Simultaneous temperature rise function | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |
| Selectable sampling cycle | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |
| Temperature input mode | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |
| Temperature control mode | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |
| Heater disconnection detection function | - | $\bullet$ | - | $\bullet$ |

Highly stable temperature control

## Standard control/heating and cooling control

Prevent overheating and overcooling in devices that require a high level of temperature stability, such as in an extrusion molding machine.
The following control methods can be selected according to the target device.

- Standard control (heating or cooling)
- Heating/cooling control (heating and cooling)
- Mix control (combination of standard control and heating-cooling control)

Example: Standard control (heating only)
The temperature of the object is controlled by adjusting the heater output based on the PID calculations resulting from the temperature sensor input.

Example: Heating-cooling control
(heating and cooling elements controlled simultaneously) Heating is performed when the control object's temperature is lower than the target temperature, and cooling is performed when it is hotter or the humidity needs to be reduced.


## Reduce running costs by taking advantage of the energy-saving effect

## Peak current control function

The peak current control function reduces the peak current by automatically changing the upper-output limit value for each channel, while dividing the transistor output timing*1. The energy conserved by reducing the peak current, such as a reduction in system power capacity and reduction in contracted power, can help to reduce running costs.
*1: The timing can be split between two to four outputs.


## Ensures uniform temperature control

## Simultaneous temperature rise function

Ensures uniform temperature control by synchronizing the temperature arrival times from multiple loops.
Perform a uniform temperature rise using two or more control loops without going over temperature or resulting in unexpected thermal expansion.
A "no idling" format increases energy efficiency and reduces running costs.
■ Example: Temperature control of injection molding machine


Example: Wafer heating process for semiconductor manufacturing


The running costs is reduced!


Using this function, it is possible to coordinate the control of two or more loops to reach their target values (SV) at the same time. Control the simultaneous rise in temperature of separate loops by setting a channel group (Max. 2 groups). This is an effective way to control applications where differing target temperature arrival times can result in undesirable temperature differentials.

## Support a range of system requirements

Sampling cycle change function
Choose a sampling cycle of $250 \mathrm{~ms} / 4$ channels or $500 \mathrm{~ms} / 4$ channels.


Sampling period: The time it takes to execute a PID operation for all channels $(\mathrm{CHn})$ before beginning the PID operation of the present channel $(\mathrm{CHn})$ again is called a sampling period.

## Temperature input mode

This function allows the temperature control module to be used as a standard temperature input module.
Using the switch setting, it is possible to easily change the input mode.

$= \pm 5.2^{\circ} \mathrm{C}$

## ■ Control mode

Control for each channel is as follows.

| Item |  |  | L60TCTT4 | L60TCTT4BW | L60TCRT4 | L60TCRT4BW |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Control output |  |  | Transistor output |  |  |  |
| Number of temperature input channels |  |  | 4 channels |  |  |  |
| Applicable temperature sensors |  |  | Thermocouple |  | Resistive thermal device |  |
| Accuracy*1 | Indication accuracy | Ambient temperature: $25 \pm 5^{\circ} \mathrm{C}$ | Full scale $\times( \pm 0.3 \%)$ |  |  |  |
|  |  | Ambient temperature: $0 \ldots . .55^{\circ} \mathrm{C}$ | Full scale $\times( \pm 0.7 \%$ ) |  |  |  |
|  | Cold junction temperature compensation accuracy: (ambient temperature: $0 . .55^{\circ} \mathrm{C}$ ) | Temperature process value (PV): <br> $-100^{\circ} \mathrm{C}$ or more | $\leq \pm 1.0^{\circ} \mathrm{C}$ |  | - |  |
|  |  | $\begin{aligned} & \text { Temperature process value (PV): } \\ & -150 \ldots-100^{\circ} \mathrm{C} \end{aligned}$ | $\leq \pm 2.0^{\circ} \mathrm{C}$ |  |  |  |
|  |  | Temperature process value (PV): $-200 \ldots-150^{\circ} \mathrm{C}$ | $\leq \pm 3.0^{\circ} \mathrm{C}$ |  |  |  |
| Sampling cycle |  |  | $250 \mathrm{~ms} / 4$ channels $500 \mathrm{~ms} / 4$ channels |  |  |  |
| Control output cycle |  |  | $0.5 . .100 .0 \mathrm{~s}$ |  |  |  |
| Input impedance |  |  | $1 \mathrm{M} \Omega$ |  |  |  |
| Input filter |  |  | $0 . .100 \mathrm{~s}$ (0: Input filter OFF) |  |  |  |
| Sensor correction value setting |  |  | -50.00...50.00\% |  |  |  |
| Operation at sensor input disconnection |  |  | Upscale processing |  |  |  |
| Temperature control method |  |  | PID ON/OFF pulse or two-position control |  |  |  |
| PID constants range |  | PID constants setting | Can be set by auto tuning. |  |  |  |
|  |  | Proportional band (P) | 0.0...1000.0\% (0: Two-position control) |  |  |  |
|  |  | Integral time (I) | $0 . .3600 \mathrm{~s}$ (set 0 for P control and PD control.) |  |  |  |
|  |  | Derivative time (D) | $0 \ldots 3600 \mathrm{~s}$ (set 0 for P control and PI control.) |  |  |  |
| Set value (SV) setting range |  |  | Within the temperature range set in the thermocouple/platinum resistance thermometer to be used |  |  |  |
| Dead band setting range |  |  | 0.1...10.0\% |  |  |  |
| Transistor output |  | Output signal | ON/OFF pulse |  |  |  |
|  |  | Rated load voltage | $10 \ldots 30 \mathrm{~V}$ DC |  |  |  |
|  |  | Max. load current | 0.1 A/point, 0.4 A/common |  |  |  |
|  |  | Max. inrush current | 0.4 A 10 ms |  |  |  |
|  |  | Leakage current at OFF | $\leq 0.1 \mathrm{~mA}$ |  |  |  |
|  |  | Max. voltage drop at ON | $1.0 \mathrm{~V} \mathrm{DC} \mathrm{(TYP)} \mathrm{at} 0.1 \mathrm{~A} 2.5 \mathrm{~V} \mathrm{DC} \mathrm{(MAX)} \mathrm{at} 0.1 \mathrm{~A}$ |  |  |  |
|  |  | Response time | OFF $\rightarrow$ ON: $\leq 2 \mathrm{~ms}, \mathrm{ON} \rightarrow \mathrm{OFF}: \leq 2 \mathrm{~ms}$ |  |  |  |
| Number of accesses to non-volatile memory |  |  | Max. $10^{12}$ times |  |  |  |
| Isolation method |  |  | Between input terminal and programmable controller power supply: Transformer isolation Between input channels: Transformer isolation |  |  |  |
| Heater disconnection detection specifications |  | Current sensor | - | - CTL-12-S36-10 (0.0...100.0 A) *2 <br> - CTL-12-S56-10 (0.0...100.0 A)*2 <br> - CTL-6-P-H ( $0.00 \ldots 20.00 \mathrm{~A}$ ) *2 | - | - CTL-12-S36-10 (0.0...100.0 A) *2 <br> - CTL-12-S56-10 (0.0...100.0 A) *2 <br> - CTL-6-P-H ( $0.00 \ldots 20.00 \mathrm{~A}$ ) *2 |
|  |  | Input accuracy |  | Full scale $\times( \pm 1.0 \%)$ |  | Full scale $\times( \pm 1.0 \%)$ |
|  |  | Number of alert delay |  | 3... 255 |  | 3... 255 |
| Module size allocation |  |  | 1 | 2 | 1 | 2 |
| Number of occupied l/O points |  |  | 16 points (//O assignment: Intelligent 16 points) |  |  |  |
| External interface |  |  | 18-point terminal block | 18-point terminal block $\times 2$ | 18-point terminal block | 18-point terminal block $\times 2$ |
| 5 V DC internal current consumption |  |  | 0.30 A | 0.33 A | 0.31 A | 0.35 A |
| Weight |  |  | 0.18 kg | 0.33 kg | 0.18 kg | 0.33 kg |

*1: Calculate the accuracy in the following method (only when it is not affected by noise).


(Full scale) $\times$ (indication accuracy) + cold junction temperature compensation accuracy
$=\left(400.0^{\circ} \mathrm{C}-\left(-200.0^{\circ} \mathrm{C}\right)\right) \times( \pm 0.007)+\left( \pm 1.0^{\circ} \mathrm{C}\right)$
*2: U.R.D.Co., LTD. For more information, visit http://www.u-rd.com

| Control mode | Contents | Number of controllable loops |
| :--- | :--- | :--- | :--- |
| Standard control | Performs the standard control of four channels. | Standard control 4 loops |
| Heating-cooling control (normal mode) | Performs the heating-cooling control. CH3 and CH4 cannot be used. | Heating-cooling control 2 loops |
| Heating-cooling control (expanded mode) | Performs the heating-cooling control. The number of loops is expanded using an output module and others in <br> the system. | Heating-cooling control 4 loops |
| Mix control (normal mode) | Performs the standard control and the heating-cooling control. CH2 cannot be used. | Standard control 2 loops <br> Heating-cooling control 1 loop |
| Mix control (expanded mode) | Performs the standard control and the heating-cooling control. The number of loops is expanded using <br> an output module and others in the system. | Standard control 2 loops <br> Heating-cooling control 2 loops |


| Channel | Standard control | Heating-cooling control |  | Mix control |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Normal mode | Expanded mode | Normal mode | Expanded mode |
| CH1 | Standard control | Heating-cooling control | Heating-cooling control | Heating-cooling control | Heating-cooling control |
| CH2 | Standard control | Heating-cooling control | Heating-cooling control | $-^{* 3}$ | Heating-cooling control |
| CH3 | Standard control | $-^{* 3}$ | Heating-cooling control | Standard control | Standard control |
| CH4 | Standard control | $-^{* 3}$ | Heating-cooling control ${ }^{* 4}$ | Standard control | Standard control |

[^3]
## 



Simple Motion Modules

*SSCNET(Servo System Controller NETwork)

| Function | LD77MS2 | LD77MS4 | LD77MS16 |
| :--- | :---: | :---: | :---: |
| Positioning control function | $\bullet$ | $\bullet$ | $\bullet$ |
| Speed/torque control function | $\bullet$ | $\bullet$ | $\bullet$ |
| Linear interpolation | 2 axes | $2 / 3 / 4$ axes | 2 axes |
| Circular interpolation | 2 axes | $\bullet$ | $2 / 3 / 4$ axes |
| Synchronous <br> control function | External encoder | $\bullet$ | $\bullet$ |
|  | $\bullet$ | $\bullet$ | $\bullet$ |
| Phase compensation | $\bullet$ | $\bullet$ | $\bullet$ |
| OPR control function | $\bullet$ | $\bullet$ | $\bullet$ |

## Positioning Modules



## LD75P1

Number of control axes: 1 axis Max. output pulses: 200 K pulses/s Max. output pulses: 200 K pulses/s ositioning data: 600 data/axis
 LD75P2
Number of control axes: 2 axis Nax output pul Max. output pulses: 200 K pulses Positioning data: 600 data/axis
Max. connection distance: 2 m

## LD75D2

Number of control axes: 2 axis Max. output pulses: 4M pulse/s Positioning data: 600 data/axis Max. connection distance: 10 m


LD75P4
Number of control axes: 4 axis Max. output pulses: 200 K pulses/s Positioning data: 600 data/axis Max. connection distance: 2 m

Number of control axes: 1 axis Max. output pulses: 4M pulse/s Positioning data: 600 data/axis Max. connection distance: 10 m

## Countless applications are possible

A variety of control types including positioning control, speed control, torque control, cam control and synchronous control can be implemented easily with simple parameter settings and a sequence program.

## Positioning control

- Support for a multitude of applications thanks to a wide variety of control formats including linear interpolation control (up to 4 axes), 2-axis circular interpolation control, fixed feed control and continuous orbit control.
- Use a sequence program to set the positioning address, speed, etc. for easy automatic operation.
- Quickly implement powerful auxiliary functions such as step operation, target position change, M codes, and the skip function.



## Speed control and torque control

- Tension control applications such as winding and rewinding are supported.
- Switch from positioning control, to speed and torque control, and back to positioning control.
Because the present location is tracked even in speed and torque control mode, it is possible to maintain the current absolute position when returning to positioning control.



## Synchronous control and cam control

- Cam control may be used alone or combined with synchronous control.


## Example application for cam control:

To create a movement path around a workpiece using positioning control, axis 2 waits for axis 1 to complete the move from P 1 to P 2 before it begins moving from P2 to P3. By using cam control, axis 2 does not need to wait for axis 1 to complete its movement and the in position time can be shortened.


## Many functions in a compact design

## Use a synchronous encoder with synchronous control

- Input pulses from a synchronous encoder can be used to perform synchronous control and cam control.
- The incremental synchronous encoder can be used by using the LD77MS built-in interface. An option unit is not required.
- To further improve the synchronization accuracy, the phase compensation function, designed to compensate for synchronous encoder delays, can be used.



## Standard mark detection function

- The built-in mark detection signal interface allows these units to be used in packaging systems for example, without additional option modules.


## Automatic cam data generation for rotary cutter

- Complicated cam data for rotary cutters can be automatically generated just by specifying a few parameters like the sheet length and synchronization width.



## Perfect synchronous control is easy to achieve

LD77MS $\square$
Replace mechanical gears, shafts, speed change gears, cams, etc. and generate synchronous control operations using software.

- Complicated programs are unnecessary for synchronous control because it can be implemented easily using parameter settings.
- Start and stop synchronous control for each axis. Use the synchronous control axis and positioning control axis together.
- Convey the travel value of main shaft to the output axis via the clutch.


Synchronous Control Parameter Settings

## Cam control made simple

LD77MS $\square$
Create cam data patterns easily.

- Create cam profiles unrestricted by existing concepts of electronic cam control.
- Change the acceleration, speed, stroke, and jerk while simultaneously seeing how it effects the profile.
- Easily check created cam data by viewing them as thumbnails.
- Import and export cam data in CSV format.



## Simplified debugging and commissioning

Digital oscilloscope function

- Collection of data from the simple motion module is synchronized with the operation cycle and waveform displays to facilitate an efficient start up.
- The assistant function explains each step.
- Use the purpose-based probe setting to easily set frequentlyviewed data.
- Sample 16 CH word and 16 CH bit data and display 8 CH words and 8 CH bits in real time.



## Monitor and test functions

- Complete the system installation and perform operational checks easily using powerful monitor and test functions.
- Select items to be displayed on the monitor using a wealth of information monitoring options.
- The test function can be used to check basic operations without a sequence program.



| Item |  |  | LD75P1/LD75D1 ${ }^{\text {¹ }}$ | LD75P2/LD75D2* | LD75P4/LD75D4* |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Number of control axes |  |  | 1 axis | 2 axes | 4 axes |
| Interpolation function |  |  | - | 2-axis linear interpolation 2-axis circular interpolation | 2-axis/3-axis/4-axis linear interpolation, 2-axis circular interpolation |
| Control system |  |  | PTP (Point To Point) control, path control (both linear and arc can be set), speed control, speed-position switching control, position-speed switching control |  |  |
| Control unit |  |  | mm , inch, degree, pulse |  |  |
| Positioning data |  |  | 600 data (positioning data No.1...600) /axis (Can be set with peripheral device or sequence program.) |  |  |
| Backup |  |  | Parameters, positioning data, and block start data can be saved on flash ROM (battery-less backup) |  |  |
| Positioning control | Positioning control system | PTP*2 control | Increment system, absolute system |  |  |
|  |  | Speed-position switching control | Increment system, absolute system*3 |  |  |
|  |  | Position-speed switching control | Increment system |  |  |
|  |  | Path control | Increment system, absolute system |  |  |
|  | Positioning control range | In absolute system | $\begin{gathered} \hline-214748364.8 \ldots 214748364.7(\mu \mathrm{~m}) \\ -21474.83648 \ldots . \ldots 1474.83647 \text { (inch) } \\ 0 \ldots 359.99999 \text { (degree) } \\ -2147483648 \ldots 2147483647 \text { (pulse) } \\ \hline \end{gathered}$ |  |  |
|  |  | In increment system | ```-214748364.8...214748364.7 ( }\mu\textrm{m} -21474.83648...21474.83647 (inch) -21474.83648...21474.83647 (degree) -2147483648...2147483647 (pulse)``` |  |  |
|  |  | In speed-position switching control (INC mode)/ position-speed switching control | $0 . . .214748364 .7$ ( $\mu \mathrm{m}$ ) <br> $0 . . .21474 .83647$ (inch) <br> $0 . . .21474 .83647$ (degree) <br> 0... 2147483647 (pulse) |  |  |
|  |  | In speed-position switching control (ABS mode) ${ }^{* 3}$ | 0...359.99999 (degree) |  |  |
|  | Speed command |  | $0.01 \ldots .20000000 .00(\mathrm{~mm} / \mathrm{min})$ $0.001 \ldots 2000000.000$ (inch/min) 0.001... 2000000.000 (degree/min) <br> 1... 4000000 (pulse/s) |  |  |
|  | Acceleration/deceleration system selection |  | Trapezoidal acceleration/deceleration, S-curve acceleration/deceleration |  |  |
|  | Acceleration/deceleration time |  | 1... 8388608 ms <br> Four patterns can be set for each of acceleration time and deceleration time |  |  |
|  | Sudden stop deceleration time |  | $1 . .8388608 \mathrm{~ms}$ |  |  |
| OPR method |  |  | 6 types |  |  |
| Starting time ${ }^{* 4}$ |  |  | 1-axis linear control |  | 1.5 ms |
|  |  |  | 1-axis speed control |  | 1.5 ms |
|  |  |  | 2-axis linear interpolation control (Composite speed) |  | 1.5 ms |
|  |  |  | 2-axis linear control (Reference axis speed) |  | 1.5 ms |
|  |  |  | 2-axis circular interpolation control |  | 2.0 ms |
|  |  |  | 2-axis speed control |  | 1.5 ms |
|  |  |  | 3-axis linear interpolation control (Composite speed) |  | 1.7 ms |
|  |  |  | 3-axis linear interpolation control (Reference axis speed) |  | 1.7 ms |
|  |  |  | 3-axis speed control |  | 1.7 ms |
|  |  |  | 4-axis linear interpolation control |  | 1.8 ms |
|  |  |  | 4-axis speed control |  | 1.8 ms |
| Maximum output pulse |  | LD75P $\square$ | 200 kpulse/s |  |  |
|  |  | LD75D $\square$ | 4 Mpulse/s |  |  |
| Maximum connection distance between drive units |  | LD75P $\square$ | 2 m |  |  |
|  |  | ts LD75D $\square$ | 10 m |  |  |
| Module size allocation |  |  | 2 |  |  |
| Number of occupied I/O points |  |  | 32 points (I/O assignment: Intelligent 32 points) |  |  |
| External interface |  |  | 40-pin connector |  | 40-pin connector $\times 2$ |
| 5 V DC internal current consumption |  | LD75P■ | 0.44 A | 0.48 A | 0.55 A |
|  |  | LD75D $\square$ | 0.51 A | 0.62 A | 0.76 A |
| Weight |  |  | 0.18 kg |  |  |

*1: LD75P $\square$ refers to the open collector output type, and LD75D $\square$ refers to the differential driver output type.
*2: The abbreviation for Point To Point, referring to position control.
*3: In speed-position switching control (ABS mode), "degree" is the only control unit available.
*4: Using the pre-reading start function, the actual starting time can be shortened.

## Flexible High-Speed I/O Control Module


*1: Abbreviation of Field Programmable Gate Array. FPGA is an LSI that can be programmed after the manufacture.

## Easy FPGA setup with dedicated configuration tool*2

The design process associated with FPGA (HDL programming, logic synthesis, timing analysis) is no longer required, drastically reducing the development time. The configuration tool is also useful to pre-check the product operation, further reducing the startup time.



- Click terminals to connect between blocks
Identify connectable terminals by colors
- Branch connection to multiple terminals
-Multiple signals connectable to one terminal

- Set function block operations by parameters
- Parameters assigned to buffer memories are accessible from CPU programs

- Check the operation with virtual inputs
-Check the simulation result on GX LogViewer

[^4]
## Supporting versatile applications

The flexible high-speed I/O control module realizes a wide range of controls including speed measurement, adjusted pulse output, ratio setting/distributed output, PWM control, and cam switch control.

Pulse adjustment

- ON/OFF timings are finely adjusted down to 25 ns by using trigger inputs.
- Fluctuation of ON/OFF operation is minimized down to nanoseconds, enabling highly precise control.

Speed measurement

- In addition to ON and OFF width, measurement in different conditions is possible, such as ON timing difference between sensors.
- The measurement increment of minimum 25 ns realizes highly accurate measurement.

Delay output

- Output timing delays are adjusted for each point, minimizing output variations.


| Item |  |  | LD40PD01 |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  |  | DC | Differential |
| Number of input points |  |  | 12 points (5/24 V DC/differential) |  |
| Number of output points |  |  | 8 points (5...24 V DC, 0.1 A/point) | 6 points |
| Number of interrupts |  |  | 8 interrupts |  |
| Input response time |  |  | $\leq 1 \mu \mathrm{~s}$ (pulse input speed: Max. $200 \mathrm{kpulse} / \mathrm{s}$ ) | $\leq 1 \mu \mathrm{~s}$ (pulse input speed: Max. 8 Mpulse/s) |
| Output response time |  |  | $\leq 1 \mu \mathrm{~s}$ (pulse input speed: Max. $200 \mathrm{kpulse} / \mathrm{s}$ ) | $\leq 1 \mu \mathrm{~s}$ (pulse input speed: Max. 8 Mpulse/s) |
| Main blocks (included in the configuration tool) |  |  |  |  |
| External input block | Logic select |  | Inverted, not inverted |  |
|  | Filter time |  | General input: $0 \mu \mathrm{~s}, 10 \mu \mathrm{~s}, 50 \mu \mathrm{~s}, 0.1 \mathrm{~ms}, 0.2 \mathrm{~ms}, 0.4 \mathrm{~ms}, 0.6 \mathrm{~ms}, 1 \mathrm{~ms}, 5 \mathrm{~ms}$ <br> Pulse input: $10 \mathrm{kpulse} / \mathrm{s}, 100 \mathrm{kpulse} / \mathrm{s}$, $200 \mathrm{kpulse} / \mathrm{s}$, $500 \mathrm{kpulse} / \mathrm{s}, 1 \mathrm{Mpulse} / \mathrm{s}$, $2 \mathrm{Mpulse} / \mathrm{s}, 4 \mathrm{Mpulse} / \mathrm{s}, 8 \mathrm{Mpulse} / \mathrm{s}$ |  |
| Parallel encoder block | Input data type |  | Pure binary, gray code, BCD |  |
|  | Data length |  | 1 bit... 12 bits |  |
| SSI encoder block | Input data type |  | Pure binary, gray code |  |
|  | Data length |  | 1 bit... 32 bits (Data length for single turn, multi-turn, and status can be set.) |  |
|  | Transmission speed |  | $100 \mathrm{kHz}, 200 \mathrm{kHz}, 300 \mathrm{kHz}, 400 \mathrm{kHz}, 500 \mathrm{kHz}, 1.0 \mathrm{MHz}, 1.5 \mathrm{MHz}, 2.0 \mathrm{MHz}$ |  |
| Multi function counter block | Counter timer block | Type | Addition, subtraction, linear counter mode, ring counter mode, addition mode, preset counter function, latch counter function, internal clock function |  |
|  |  | Internal clock | $25 \mathrm{~ns}, 50 \mathrm{~ns}, 0.1 \mu \mathrm{~s}, 1 \mu \mathrm{~s}, 10 \mu \mathrm{~s}, 100 \mu \mathrm{~s}, 1 \mathrm{~ms}$ |  |
|  |  | Counting range | 32-bit signed binary (-2147483648...2147483647), 32-bit unsigned binary ( $0 . .4294967295$ ) 16 -bit signed binary ( -32768 ... 32767 ), 16 -bit unsigned binary ( $0 . . .65535$ ) |  |
|  | Compare block | Compare value | Same as the counting range |  |
|  |  | Compare mode | $=,>,<, \geq, \leq,<>$, within the range, outside the range |  |
|  | Cam switch block number of steps |  | Up to 16 steps |  |
|  | Set/reset block |  | Uses the signal input to the Set terminal as a trigger to output the High fixed signal. Uses the signal input to the Reset terminal as a trigger to output the Low fixed signal. |  |
| Logical operation block | Logical o | peration type | AND, OR, XOR |  |
| External output block | Logic select |  | Inverted, not inverted |  |
|  | Delay time |  | None, $12.5 \mathrm{~ns}, 25 \mathrm{~ns}, 50 \mathrm{~ns}, 0.1 \mu \mathrm{~s}, 1 \mu \mathrm{~s}, 10 \mu \mathrm{~s}, 100 \mu \mathrm{~s}, 1 \mathrm{~ms}$ Can be set up to 64 multiplies. |  |
| Main functions that can be performed with the combination of main blocks |  |  | Pulse count, coincidence detection, cam switch, highly-accurate pulse output, PWM output, ratio setting, pulse measurement, electrical interface conversion |  |
| Processing time of the main hardware logic |  |  | Logic operation: Min. 87.5 ns, Coincidence output: Min. 137.5 ns, Cam switch: Min. 262.5 ns |  |
| Module size allocation |  |  | 2 |  |
| Number of occupied I/O points |  |  | 32 points (1/O assignment: Intelligent 32 points) |  |
| External interface |  |  | 40-pin connector $\times 2$ |  |
| 5 V DC internal current |  |  | 0.66 A |  |
| Weight |  |  | 0.18 kg |  |

High-Speed Counter Modules


| Function | LD62 | LD62D |
| :--- | :---: | :---: |
|  | DC input | Differential input |
| Linear counter function | $\bullet$ | $\bullet$ |
| Ring counter function | $\bullet$ | $\bullet$ |
| Coincidence output function | $\bullet$ | $\bullet$ |
| Preset function | $\bullet$ | $\bullet$ |
| Disable count function | $\bullet$ | $\bullet$ |
| Latch counter function | $\bullet$ | $\bullet$ |
| Sampling counter function | $\bullet$ | $\bullet$ |
| Periodic pulse counter function | $\bullet$ | $\bullet$ |



## Seamless integration of multiple networks

The MELSEC L Series is part of a family of products all interconnected across various levels of automation. Based on the seamless message protocol (SLMP*1), data flows transparently between the sensor level and the management level across multiple industry-standard automation networks. CC-Link IE, Asia's No. 1 industrial network, realizes fast gigabit data transmission speeds, further optimizing the manufacturing cycle. In addition, the SSCNET 3/H high-speed motion control network further enhance the factory-wide connectivity solution.


## Seamless communication

Seamless data communication through Ethernet, CC-Link IE Control, CC-Link IE Field, and CC-Link networks allow easy access to information, no matter where it resides on the network. Through this technology, it is possible to "drill down" from the Enterprise or IT layer through multiple networks accessing programming controllers using GX Works2 programming or other related software.
In addition, many devices supporting SLMP*1 such as vision sensors and RFID controllers may be connected to the CC-Link IE Field Network.
*1: SLMP (SeamLess Message Protocol) is a protocol advocated by the CC-Link Partner Association.

## CC-Línk IE Control

CC-Link IE Control is a high-reliability distributed control network designed to handle very large data communications ( 128 K word) over a high-speed ( 1 Gbps ) dual-loop optical cable topology.
*: L Series does not support the CC-Link IE Control Network.

## CC-Link

CC-Link is a high-speed and high-reliable deterministic I/O control network which realizes reduced wiring whilst offering multi-vendor compatible products. This open field network is a global standard originating from Japan and Asia.
*: Compatible modules: L26CPU-BT, L26CPU-PBT, LJ61BT11

## CC-Link/LT

CC-Link/LT is a wire-saving sensor level network which is designed for use in panels between simple discrete devices. Its wiring system is based on reducing incorrect wiring and is based on CC-Link realizing high-speed and robust noise resistance features
*: Compatible module: LJ61CL12

## BACnet ${ }^{\text {™ }}$

This network supports the communication protocol standard BACnet ${ }^{\text {TM }}$ client function. This network is mainly used to monitor and control airconditioning, lighting and fire detection, etc. in building automation system applications.
*: Compatible modules: L02CPU(-P), L06CPU(-P), L26CPU(-P), L26CPU-(P)BT, LJ71E71-100 (client only)


## CC-Línk IE Field

CC-Link IE Field is a versatile gigabit Ethernet-based network integrating controller, I/O control, safety control, and motion control in a flexible wiring topology supporting star, ring, and line configurations. *: Compatible modules: LJ71GF11-T2, LJ72GF15-T2

## 

SSCNETIII/H is a dedicated high-speed, high-performance, and highly reliable servo system control network that offers flexible long distance wiring capabilities based on optical fiber cable topology.
*: Compatible modules: LD77MS2, LD77MS4, LD77MS16, LJ72MS15

## MODBUS®

L-Series is now supporting the MODBUS ${ }^{\oplus}$ protocol network, realizing easy communication, with various MODBUS ${ }^{\circledR}$ slave devices compatible with Ethernet MODBUS ${ }^{\circledR} / T C P$ or RS-232/422/485 serial communication
*: Module supporting MODBUS ${ }^{\oplus} /$ TCP: LO2CPU(-P), LO6CPU(-P), L26CPU(-P),
L26CPU-(P)BT, LJ71E71-100 (master only)
*: Modules supporting MODBUS ${ }^{\text {: }: ~ L 6 A D P(-R 2 / R 4), ~ L J 71 C 24(-R 2) ~(m a s t e r ~ o n l y) ~}$

## CC-Link IE Field Network Master/Local Module

## Easy to configure settings

Network parameters are configured using the engineering tool, GX Works2. Only the master station needs to be configured, thereby greatly simplifying the network setup. Updating the system configuration is a breeze.


Flexible network topology
Various network topologies are supported including star, line, star and line combination, and ring. When hubs ${ }^{* 1}$ are used, new equipment can be added and machine layouts can be changed easily.
*1: Hubs cannot be used in a ring configuration.



CC-Link IE Field Network Head Module

CC-Link IE Field | LJ-Link IE Field Intelligent device station |
| :--- |
| Communication speed: 1 Gbps |
| Remote I/O: 2048 points |
| Remote register: 1024 words |
| RAS function |
| $*:$ END cover is included. |

## CC-Link IE Field Network remote I/O station

L Series I/O and intelligent function modules can be connected to the remote I/O head module without a dedicated CPU. There are many benefits to using intelligent device stations including reduced CPU and wiring costs, great flexibility in selecting I/O and intelligent function modules, and compact unit size.

Modules compatible with the CC-Link IE Field Network head module

| Item |  |
| :--- | :--- |
| I/O module | Input, output, I/O combined |
| Multiple input module | Multiple input (voltage/current/ <br> temperature) |
| Analog module | Analog input, analog output, <br> analog input/output |
| Temperature input module | RTD input |
| Temperature control module |  |
| Simple motion module |  |
| Positioning module |  |
| High-speed counter module |  |
| Network module | CC-Link, CC-Link/LT, <br> serial communication |
| AnyWireASLINK master module |  |

## RAS (Reliability, Availability, Serviceability) functions

One feature of RAS is to store all remote station error histories in the master station's latched memory. This preserves the error information in one place in the event of power loss and allows for easy troubleshooting. Other RAS features include network event logging, unit error logging, and testing and monitoring capabilities.


| Item |  | LJ72GF15-T2 |
| :---: | :---: | :---: |
| Transmission speed |  | 1 Gbps |
| Maximum overall cable distance (Maximum transmission distance) | Line network topology | 12000 m (with 1 master and 120 slaves connected) |
|  | Star network topology | Depends on the system configuration |
|  | Ring network topology | 12100 m (with 1 master and 120 slaves connected) |
| Transmission path |  | Line, star, line and star mixed, or ring topology |
| Communication method |  | Deterministic (token passing) |
| Maximum number of installable modules ${ }^{* 1}$ |  | 10 |
| Communication port |  | CC-Link IE Field Network port x 2 |
| RAS function |  | Network event logging, unit error logging, testing, monitoring, and error history preservation function |
| Connection cable*2 |  | Ethernet cable of category 5 e or higher (Double shielded cable) which satisfies 1000 BASE-T standard |
| 5 V DC internal current consumption |  | 1.00 A |
| Weight |  | 0.23 kg |

[^5]
## CC-Link Master/Local Module



## LJ61BT11

CC-Link master/local station
Max. communication speed: 10 Mbps Remote I/O: 8192 points ${ }^{\text {1 }}$
Remote register: 2048 words ${ }^{1}$
*1:Link points for CC-Link Ver. 2.0 master station

## Connect with a huge selection of device types using CC-Link

With such a large selection of CC-Link open network compatible devices, constructing a control system is easy.
Even applications requiring vast amounts of data transmissions can be satisfied because CC-Link Ver.2.0 is supported.


Local stations do not require transmission speed settings

## Transmission speed auto-tracking function

When used as a local station, no transmission speed setting is required; the setting is made through automatic detection of the master station setting. The current transmission speed is indicated by an LED on the front surface of the module.


Specifications


## CC-Link/LT Master Module

${ }^{*}$ : When in 16 -point mode

High speed equipment response
CC-Link/LT has an excellent response time. With 64 stations
■ CC-Link/LT link scan time (using a transmission speed of 2.5 Mbps ) and a transmission speed of 2.5 Mbps , the maximum link scan time is just 1.2 ms . According to the transmission distance required, it is possible to select speeds of $2.5 \mathrm{Mbps}, 625 \mathrm{kbps}$, or 156 kbps.


## Simple networking that 'just works'

There are no confusing parameters settings to make, and with remote I/O, only the master station needs to set the transmission speed.

| Item |  |  |  | LJ61CL12 |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Point mode |  |  |  | 4-point mode | 8-point mode | 16-point mode |
| Control specifications | Maximum link points (the same I/O address used) |  |  | 256 points (512 points) | 512 points (1024 points) | 1024 points (2048 points) |
|  | Link points per station (the same I/O address used) |  |  | 4 points (8 points) | 8 points (16 points) | 16 points (32 points) |
|  | Link scan time | 32 stations connected | Points | 128 points | 256 points | 512 points |
|  |  |  | 2.5 Mbps | 0.7 ms | 0.8 ms | 1.0 ms |
|  |  |  | 625 kbps | 2.2 ms | 2.7 ms | 3.8 ms |
|  |  |  | 156 kbps | 8.0 ms | 10.0 ms | 14.1 ms |
|  |  | 64 stations connected | Points | 256 points | 512 points | 1024 points |
|  |  |  | 2.5 Mbps | 1.2 ms | 1.5 ms | 2.0 ms |
|  |  |  | 625 kbps | 4.3 ms | 5.4 ms | 7.4 ms |
|  |  |  | 156 kbps | 15.6 ms | 20.0 ms | 27.8 ms |
| Communication specifications | Transmission speed |  |  | $2.5 \mathrm{Mbps} / 625 \mathrm{kbps} / 156 \mathrm{kbps}$ |  |  |
|  | Communication method |  |  | BITR method (Broadcast polling + Interval Timed Response) |  |  |
|  | Network topology |  |  | T-branch type |  |  |
|  | Error control system |  |  | CRC |  |  |
|  | Number of connectable modules |  |  | 64 |  |  |
|  | Remote station number |  |  | 1... 64 |  |  |
|  | Installation position of master station |  |  | End of a trunk line |  |  |
|  | RAS function |  |  | Network diagnostics, internal loopback diagnostics, slave station cutoff function, automatic return function |  |  |
|  | Connection cable*2 |  |  | Dedicated flat cable ( $\left.0.75 \mathrm{~mm}^{2} \times 4\right)^{\star 3}$, VCTF cable ${ }^{* 4}$, flexible cable*3 |  |  |
| Module size allocation |  |  |  | 1 |  |  |
| Number of occupied I/O points*5 |  |  |  | 16, 32, 48, 64, 128, 256, 512, or 1024 points (I/O assignment: Intelli.) |  |  |
| 5 V DC internal current consumption |  |  |  | 0.16 A |  |  |
| 24 V DC power supply* ${ }^{*}$ |  | Voltage |  | 20.4..28.8 V DC |  |  |
|  |  | Current consumption |  | 0.03 A |  |  |
|  |  | Current on | artup | 0.07 A |  |  |
| Weight |  |  |  | 0.12 kg |  |  |

[^6]
## SSCNET III/H Head Module

## SSCNET III/H remote station

The SSCNET III/H head module is used to connect the MELSEC-L Series I/O and intelligent function modules to the SSCNET III/H network.
Functioning as the motion controller's remote station, flexible system configuration can be achieved while realizing reduced system wiring and a smaller footprint. In addition, modules installed on the SSCNET III/H head module can be used as a motion controller input/output using cyclic transmission.


■ SSCNET III/H head module compatible modules

| Product |  |
| :--- | :--- |
| I/O module | Input, output, I/O combined |
| Multiple input module | Multiple input (voltage/current/ <br> temperature) |
| Analog module | Analog input, analog output, <br> analog I/O combined |
| Temperature input module | RTD input |
| High-speed counter modules |  |
| Compatible motion controller |  |
| Category | Q172DSCPU |
| Motion CPU $\quad$ Q173DSCPU |  |
| Standalone motion controller | Q170MSCPU |


| Item |  | LJ72MS15 |
| :---: | :---: | :---: |
| Maximum link points per network | RWr, RX | 256 bytes |
|  | RWw, RY | 256 bytes |
| Maximum link points per station | RWr, RX | 64 bytes |
|  | RWw, RY | 64 bytes |
| Communication speed |  | 150 Mbps |
| Maximum connectable stations per network ${ }^{* 1}$ | Communication cycle: $888 \mu \mathrm{~s}$ | 4 |
|  | Communication cycle: 444 s | 2 |
|  | Communication cycle: $222 \mu \mathrm{~s}$ | 1 |
| Maximum station-to-station distance |  | POF type: $20 \mathrm{~m}, \mathrm{H}-\mathrm{PCF}$ type: 50 m |
| Connection method |  | Daisy chain connection (Regenerative relay system with a servo amplifier) |
| Synchronous method |  | Synchronization of the control cycle and communication cycle that synchronize with the data transmission of the motion controller |
| Communication cycle |  | $222 \mu \mathrm{~s} / 444 \mu \mathrm{~s} / 888 \mu \mathrm{~s}$ |
| Maximum number of installable modules ${ }^{* 2}$ |  | 10 |
| Communication port |  | SSCNET III/H port x2 |
| Connection cable |  | SSCNET III cable (optical fiber cable) |
| 5 V DC internal current consumption |  | 0.55 A |
| Weight |  | 0.20 kg |
| *2: Total number of modules that can be installed onto a SSCNET III/H head module. (Does not include the END cover or power supply module.) Note that only one head module per system is possible. |  |  |

Ethernet Interface Module

## Modify/collect CPU data from other devices

## SLMP (MC protocol) communication ${ }^{\star 1}$

SLMP (Seamless Message Protocol) realizes seamless communication across devices on Ethernet that support the SLMP protocol.
*1: This function can be used with modules with first five serial number digits are " 15042 " or later.


## MELSOFT connection

The MELSOFT connection feature realizes the connection to various MELSOFT products including the GX Works2 programming tool. In addition, by using together with the MX Component communication support tool (optional product), custom communications programs can be created, without having to consider any dedicated protocol (send/ receive procedure).

## Easily connect to BACnet ${ }^{\text {™ }}$ and MODBUS ${ }^{\circledR} / T C P$

## Predefined Protocol support function

Use the GX Works2 Predefined Protocol support function to easily set the required protocol for communicating with other devices.

- Selecting from the communication protocol library Easily communicate with target devices by selecting a
 prepared protocol. The communication protocol library supports the SLMP, MODBUS ${ }^{\otimes} / T C P$ and BACnet ${ }^{\text {TM }}$ client functions.
- Randomly preparing and editing a protocol

By creating a random protocol with the predefined protocol support function, data can be exchanged with a protocol that matches the target device.
$\square$ Specifications

| Item |  |  | LJ71E71-100 |  |
| :---: | :---: | :---: | :---: | :---: |
| Standard |  |  | 100 BASE-TX | 10 BASE-T |
| Transmission specifications | Data transmission speed |  | 100 Mbps | 10 Mbps |
|  | Interface |  | RJ45 (AUTO MDI/MDI-X) |  |
|  | Communication mode |  | Full duplex/Half duplex | Half duplex |
|  | Transmission method |  | Base band |  |
|  | Maximum segment length |  | 100 m (length between a hub and node)*2 |  |
|  | Maximum number of cascade connections |  | Cascade connection (maximum of 2 levels)*3 | Cascade connection (maximum of 4 levels)*3 |
| Sending/ receiving data storage memory | Number of simultaneous open connections |  | 16 connections (Connections usable on a program) |  |
|  | Fixed buffer |  | 1 K word $\times 16$ |  |
|  | Random access buffer |  | 6 K words $\times 1$ |  |
|  | E-mail | Attachment | 6 K words $\times 1$ |  |
|  |  | Main text | 960 words $\times 1$ |  |
| Module size allocation |  |  | 1 |  |
| Number of occupied I/O points |  |  | 32 points (I/O assignment: Intelligent 32 points) |  |
| 5 V DC internal current consumption |  |  | 0.60 A |  |
| Weight |  |  | 0.18 kg |  |
| *2: For the maximum segment length (a length between hubs), consult with the manufacturer of the switching hub used. <br> *3: This applies when a repeater hub is used. For the number of levels that can be constructed when a switching hub is used, consult with the manufacturer of the switching |  |  |  |  |

## Serial Communication Modules



## Quick connection using predefined protocols

The predefined protocol enables easy setup of protocols to communicate with external devices using GX Works2. Connections are quickly setup by selecting the target device from the communications protocol library.


## Easy to create/edit of predefined protocols

Easily create or edit predefined protocols from within the communications library.
Even if the target device protocol is not listed, it can be added easily to the existing library.


The data can be edited as needed.


Specifications

| Item |  | LJ71C24 | LJ71C24-R2 |  |
| :---: | :---: | :---: | :---: | :---: |
| Interface | CH 1 | RS-232 compliant (D-Sub 9P female) | RS-232 compliant (D-Sub 9P female) |  |
|  | CH 2 | RS-422/485 compliant (2-piece terminal block) | RS-232 compliant (D-Sub 9P female) |  |
| Communication system | Line | Full-duplex/half-duplex communications |  |  |
|  | MC protocol | Half-duplex communications |  |  |
|  | Predefined protocol | Full-duplex/half-duplex communications |  |  |
|  | Nonprocedural protocol |  |  |  |
|  | Bidirectional protocol |  |  |  |
| Synchronization method |  | Asynchronous method |  |  |
| Transmission speed |  | $50 \mathrm{bps} / 300 \mathrm{bps} / 600 \mathrm{bps} / 1200 \mathrm{bps} / 2400 \mathrm{bps} / 4800 \mathrm{bps} / 9600 \mathrm{bps} / 14.4 \mathrm{kbps} /$ <br> $19.2 \mathrm{kbps} / 28.8 \mathrm{kbps} / 38.4 \mathrm{kbps} / 57.6 \mathrm{kbps} / 115.2 \mathrm{kbps} / 230.4 \mathrm{kbps}$ <br> Transmission speed 230.4 kbps is only available for channel 1. <br> Total transmission speed of two interfaces is available up to 230.4 kbps . <br> Total transmission speed of two interfaces is available up to 115.2 kbps when the communication data monitoring function is used. |  |  |
| Data format | Start bits | 1 |  |  |
|  | Data bits | 7 or 8 |  |  |
|  | Parity bits | 1 (vertical parity) or none |  |  |
|  | Stop bits | 1 or 2 |  |  |
| Error detection | Parity check | All protocols and when ODD/EVEN is selected by parameter. |  |  |
|  | Sum check code | MC protocol/bidirectional protocol selected by parameter. <br> For the predefined protocol, whether or not a sum check code is needed depends on the selected protocol. Nonprocedural protocol selected by user frame. |  |  |
| Transmission control |  |  | RS-232 | RS-422/485 |
|  |  | DTR/DSR (ER/DR) control | $\bullet$ | - |
|  |  | RS/CS control | $\bullet$ | - |
|  |  | CD signal control | $\bullet$ | - |
|  |  | DC1/DC3 (Xon/Xoff) control DC2/DC4 control | $\bullet$ | $\bullet$ |
|  |  | - DTR/DSR signal control and DC code control are selected by the user. |  |  |
| Module size allocation |  | 1 |  |  |
| Number of occupied I/O points |  | 32 points (//O assignment: Intelligent 32 points) |  |  |
| 5 V DC internal current consumption |  | 0.39 A |  |  |
| Weight |  | 0.17 kg | 0.26 A |  |

## AnyWireASLINK Master Module



LJ51AW12AL
AnyWireASLINK master station
Transmission distance: Max. 200 m
Data I/O: Max. 512 points ${ }^{\star}$
Number of connected stations: Max. 128 modules
*1: 256 input points/256 output points

## AnyWireASLINK

## Linking the sensor I/O with the programmable controller

The AnyWireASLINK master module links the sensor inputs and outputs to the programmable controller.
The module enables flexible layout of miniature sensors with 512 I/O points.
The sensor power can be supplied to the AnyWireASLINK transmission line (2-wire) for communication, allowing sensors to be added easily.
With the MELSEC-Q/L/F Series, faulty sensors can be detected and the slave module settings can be managed at once by GX Works2 engineering environment, further reducing the engineering time.

## Basic configuration

Either the 2-wire type or 4-wire slave device can be selected according to the load current for AnyWireASLINK. In addition to the 2-wire type, a 4-wire type can also be used by supplying the local power.

## 2-wire type

If the load current is low, 2-wire type (non-insulated) slave devices can be used without an external power supply.

Configuration with 2-wire type (with no local power feed)


## 4-wire type

The 4-wire type (insulated) slave devices require an external 24 V DC power supply to satisfy large load current applications, for example.

## Configuration with 2-wire/4-wire type (with local power feed)



* External power for 4-wire type wiring


## Preventing intermittent operation stops

AnyWireASLINK can be used to monitor and save the sensor information within the programmable controller. Parameter settings of the AnyWireASLINK can also be changed via the programmable controller. Perform "preventive maintenance" with this function to prevent intermittent stops before they happen.

Prevent intermittent stops with preventive maintenance!

- Start maintenance early by checking the incoming light amount.
- Change the ON/OFF sensitivity to keep operating up to the maintenance period.


Reducing the setup time, and providing the traceability
AnyWireASLINK enables the set value to be registered at once to multiple sensors via a GOT (HMI) or personal computer. Also, the initial set values can be re-confirmed easily without having to read each sensor individually.

- Register set values to multiple sensors, and automatically read the initial set values.


| Item | LJ51AW12AL ${ }^{\text {dB }}$ |
| :---: | :---: |
| Transmission clock | 27.0 kHz |
| Maximum transmission distance (overall length) | 200 m ${ }^{\text {1 }}$ |
| Transmission method | DC power superimposed total frame cyclic method |
| Connection style | Bus type (multi-drop method, T-branch method, tree branch method) |
| Transmission protocol | Dedicated protocol (AnyWireASLINK) |
| Error control | Checksum, double verification method |
| Number of connected I/O points | Max. 512 points (256 input points/256 output points) |
| Number of connected modules | Max. 128 modules (varies according to each slave module's current consumption) |
| RAS function | Transmission cable break position detection function, transmission cable short-circuit detection function, transmission power drop detection function |
| Transmission cable (DP, DN) | - UL compatible universal 2-wire cable (VCTF, VCT $1.25 \mathrm{~mm}^{2}, 0.75 \mathrm{~mm}^{2}$, rated temperature $70^{\circ} \mathrm{C}$ or more) <br> - UL compatible universal cable ( $1.25 \mathrm{~mm}^{2}, 0.75 \mathrm{~mm}^{2}$, rated temperature $70^{\circ} \mathrm{C}$ or more) <br> - Dedicated flat cable ( $1.25 \mathrm{~mm}^{2}, 0.75 \mathrm{~mm}^{2}$, rated temperature $90^{\circ} \mathrm{C}$ ) |
| Power cable ( $24 \mathrm{~V}, 0 \mathrm{~V}$ ) | - UL compatible universal 2-wire cable (VCTF, VCT $0.75 \mathrm{~mm}^{2} \ldots .2 .0 \mathrm{~mm}^{2}$, rated temperature $70^{\circ} \mathrm{C}$ or more) <br> - UL compatible universal cable ( $0.75 \mathrm{~mm}^{2} . . .2 .0 \mathrm{~mm}^{2}$, rated temperature $70^{\circ} \mathrm{C}$ or more) <br> - Dedicated flat cable ( $1.25 \mathrm{~mm}^{2}, 0.75 \mathrm{~mm}^{2}$, rated temperature $90^{\circ} \mathrm{C}$ ) |
| Transmission cable supply current*2 ${ }^{\text {2 }}$ | Using $1.25 \mathrm{~mm}^{2}$ cable: Max. 2 A Using $0.75 \mathrm{~mm}^{2}$ cable: Max. 1 A |
| Module size allocation | 1 |
| Number of occupied I/O points | 32 points (//O assignment: 32 intelligent points) |
| External power supply | Voltage: 21.6...27.6 V DC (24 V DC -10...+15\%), ripple voltage $0.5 \mathrm{Vp}-\mathrm{p}$ or less Recommended voltage: 26.4 V DC ( 24 V DC $+10 \%$ ) <br> Module current consumption: 0.1 A <br> Transmission cable current supply: Max. 2 A*1 |
| 5 V DC internal current consumption | Max. 0.2 A |
| Weight | 0.2 kg |

*1: With the slave module having an integrated transmission cable (DP, DN) and module, the length of the transmission cable (DP, DN) is included in the overall length.
${ }^{*}$ 2: Refer to the manual for the relation of the overall length, transmission cable (DP, DN) wire diameter and transmission cable current supply. In some slave modules with cables, the wire diameter of the transmission cable (DP, DN) integrated with the module may be $0.75 \mathrm{~mm}^{2}$ or less.


## GXWロгksZ

GX Works2 focuses on driving down total cost by including features that speed up commissioning, reduce downtime, improve programming productivity, and provide strong security.

## User interface that is "easy to use" by design

The programming tool GX Works2 has been developed from the ground up to be intuitive for all users and allow anyone to begin programming easily. The user interface and other functions provide a comfortable programming environment that enables improvements in design efficiency.


## Easily create circuits with few key inputs

The program can be easily modified using the keyboard shortcut [ Alt ] + [ $\leftarrow] /[\rightarrow]$ or [ Alt ] + [ $\uparrow$ ]/ [ $\downarrow$ ] keys.



## Simple Motion/ Positioning <br> Flexible I/O/ High-Speed Counter <br> Network

## Efficiently edit lines with keyboard

Ladder rungs can be easily modified just by using the various keyboard shortcut keys, eliminating the need to switch to editing mode.


Input line with $+\infty$ or $+\infty$
Input lines up to coil in batch with $+\infty$$\pm$

How to input a line
Press [Ctrl] $+[\rightarrow]$ or [Ctrl] $+[\downarrow]$
at an empty spot.
Press [Ctrl] $+[\rightarrow]$ or $[\mathrm{Ctrl}]+[\downarrow]$
on top of a line to delete it.


## Use function blocks for common operations

Function blocks allow selections of commonly used code to be easily reused and shared among projects. Shared or created function blocks can be added to a program using simple drag and drop operation. Using function blocks effectively results in faster development times with fewer programming mistakes.


Use sample comments to eliminate the need to input comments
Sample comments are provided for the CPU's special relays/registers and the intelligent function module's buffer memory/XY signals. These can be copied into the project's comments thus greatly reducing the time required for entering device comments.


## Quickly identify similar devices

Word device comments can be registered per bit with the contents displayed directly on the ladder rung.


## Cross referencing interlinked with circuit displays

Relevant devices and labels can be searched within the contents of the program by using the cross reference tool. The results are immediately displayed in the cross reference dialog box conveniently besides the actual program view screen. It is then very easy to check where the relevant device is actually used within the program, just by double clicking on the target device.


The simulation function is now integrated. The program can be executed in a step-by-step method, finding program errors more easily.


Integrating the intelligent function module setting tool (GX Configurator)
The intelligent function module's setting functions have been unified with GX Works2.
Manage the intelligent function module's setting with a GX Works2 project.


Operation status of the entire programmable controller system is clearly displayed. Each module's diagnosis and detailed information are displayed enabling faster troubleshooting.

## System monitor and PLC diagnostics



## Time-stamped error history list

Simplify troubleshooting with a combined, time-stamped, error history list for the CPU and all expansion modules. The details section provides explanations of error codes and suggested solutions.


## Set parameters and monitor the sensor

Parameter settings and monitoring can be performed on the third-party partner products, which support the iQ Sensor Solution (iQSS). Sensor connection and current values can be checked visually, allowing the user to act faster in case of a trouble.



# MELSOFT iQ Works Next Generation Integrated Engineering Environment 

MELSOFT iQ Works is an integrated software suite consisting of GX Works3, GX Works2, MT Works2, GT Works3, RT ToolBox2 mini and FR Configurator2. The advantages of this powerful integrated software suite are that system design is made much easier with a substantial reduction in repetitious tasks, cutting down on errors while helping to reduce the overall TCO.

## Graphical project management

The entire control system is represented using the "Network Configuration", "Module Configuration" and field network configuration windows. System components are easily added using a drag \& drop interface, and the validity of the system can be confirmed using the check function to ensure parameters are configured correctly, the power supply is sufficient, etc. Different programmable controller and GOT (HMI) projects can be grouped together (for example by factory, line, and cell) for central management.


Read project data for multiple devices in a batch
Multiple projects can be read as a block just by having one connection to the programmable controller. If there are multiple devices such as other CPU or GOT(HMI) on the same network as the target master programmable controller, it is possible to upload all projects to each target device without having to individually connect to each device.

Automatically start up the relevant maintenance software with a single click
Just double-click on the corresponding project in the system configuration diagram or workspace tree to automatically startup the software relevant for that device. Maintenance can be efficiently performed without having to know and startup each relevant software manually.


Set up field network slave stations
There's no need to prepare a dedicated tool to check or change the parameter settings of a slave station on-site. The latest version of $\mathrm{i} Q$ Works includes slave station setting utility. Inverter parameters, for example, can be confirmed or changed for speed adjustment directly from the field network configuration window. In addition, error information can be read easily.

CC-Línk IE FField


A list of modules used can be exported as a CSV file from the system configuration diagram.
This is particularly useful when utilizing data for creating a bill of materials (BOM) in Excel ${ }^{\oplus}$, etc.

## AnyWireASLINK

## Ethernet

## Prepare a device from the system configuration diagram with no manual inputs



## GX LogViewer <br> Visualizing the production process

Within modern manufacturing needs, data collection has become more important for fully optimizing the production process. GX LogViewer is a software tool that realizes visualization of large amounts of production data in a simple to use format.
Utilizing this functionality to identify root error causes and improving the production rate.

## Easily display and analyze large amounts of collected logging data

This tool is used when large amounts of data need to be visualized and collected from the MELSEC-Q Series or MELSEC-L Series.
The connection settings and checking of log files are the same as GX Works2 enabling individual connections to each module.


## Easily adjust graphs without referring to the setup manual

## Arranging graphs

Able to arrange each graph so as not to overlap each other. It is easier to display the graphs as each graph is evenly spaced out.


## Overlapping graphs

With this it is possible to overlap each graph over one another. Multiple graphs can be compared enabling easier data analysis and comparison.


## Automatically adjusting graphs

Various attributes of the graph are automatically adjusted (max/min values) as to display the upper and lower limit values better.


## Easily confirm changes in data with dual cursors

Data changes within a designated time frame can be quickly checked with user-friendly dual cursors (multi-cursors). When the cursors are moved to the point at which changes are to be confirmed, the difference in time and value between those points will appear.

$\bar{\jmath}$

Display data for multiple files within one graph area for easy comparison
Data for multiple files are displayed with the same time units in the same graph area. The display position within a file can be moved easily. This allows the differences of data within multiple files to be confirmed easily.


## Quickly jump cursor to designated position

## Cursor jump

Confirm data values by quickly moving the cursor to a designated value, time or index position in the trend graph.



Value search
Values are searched, and the cursor jumps to the position where the conditions match.


Time designation
The cursor jumps to the designated time.


Index designation
The cursor jumps to the designated index.

# A tool for connecting! Visualizing! For a more seamless sensor control! 

## iQ Sensor Solution

iQSS connects everything from
general to advanced sensors.

Sensors used on the manufacturing floor are becoming more intelligent and complex, requiring even more maintenance of equipment and the overall management of various configuration setup software. With iQSS, the intelligent sensor solution provided by Mitsubishi Electric, configuration and maintenance of sensors are further simplified with the connectivity to other components such as automation controllers, HMIs, and engineering software even further enhanced reducing the overall TCO*. * Total Cost of Ownership

Ethernet
CC-Línk IE Eield

CC-Link
AnyWireASLINK



Ser


## Vision Solution

# COGNEX ${ }^{\circledR}$ machine vision system and Mitsubishi Electric FA Devices 

 Innovating your production with this integral power.Functioning as devices that "watch" instead of human eyes, COGNEX machine vision systems have continued to reform automation of production lines. Mitsubishi Electric FA devices, such as programmable controllers, lead the future of automation.
The possibilities of vision system solutions, created in the integration of this spirit of innovation, have continued to increase.

## L(NA)08230E

For further details, please refer to the "Vision System \& Factory Automation Solution Catalog".

## COGNEX DataMan® Barcode Reader Device parther

- Fixed DataMan
- Hand-held DataMan ......... DataMan 8050/8100/8500

DataMan - active in various industries


Automotive components


Aero


Medical
Medical
devices


Electronic Electronic
components

## -Fixed DataMan 50/60

- Unmatched read rate performance with Hotbars ${ }^{\text {TM }}$
- Proprietary Hotbars ${ }^{\text {TM }}$ technology

- Solid state design with no moving parts

DataMan 50

- Easy setup with three position adjustable lens and integrated lighting aimer
- IP65-rated housing (DataMan 50)
- Supports SLMP (DataMan 60)


DataMan 60

## -Fixed DataMan 300 Series

- Unprecedented read rate with Hotbars ${ }^{\text {TM }}$

Reads the most difficult-to-read 2-D Direct Part Mark (DPM) codes
Liquid lens with automatic variable focus

- Intelligent tuning
- Integrated lighting module


Supports SLMP


Programmable controller

## -Hand-held DataMan 8050/8100/8500 Series

UltraLight®: Two types of lighting enable optimum reading*1

- Newly developed body enhances sturdiness
- Standard automatic focus adjustment function*2
- Supports SLMP
- Cordless capability
(up to 30 m communication range)
- Unprecedented read rate with Hotbars ${ }^{\top}{ }^{\top}$
*1: DataMan 8500



## CPU modules

L02SCPU, L02SCPU-P


L02CPU, L02CPU-P, L06CPU, L06CPU-P, L26CPU, L26CPU-P


L26CPU-BT, L26CPU-PBT


Display unit
L6DSPU

## RS-232 adapter

L6ADP-R2


## RS-422/485 adapter

L6ADP-R4


## END cover with error terminal

L6EC-ET


## Power supply modules

L61P, L63P
L63SP

## Branch module

L6EXB




## Extension cable

LC06E, LC10E, LC30E


Input/Output///O combined modules
LX10, LX28, LX40C6, LY10R2, LY18R2A
LY20S6, LY28S1A, LY40NT5P, LY40PT5P



LX42C4, LY42NT1P, LY42PT1P
LH42C4NT1P, LH42C4PT1P


LG69
L6TE-18S


## Multiple input (voltage/current/temperature)/Analog input/output//O module

L60MD4-G, L60AD4, L60DA4, L60ADVL8, L60ADIL8, L60AD4-2GH, L60AD2DA2


## Temperature input module

L60RD8


## L60TCTT4, L60TCRT4



## L60TCTT4BW, L60TCRT4BW



## Simple motion modules

LD77MS2, LD77MS4, LD77MS16


## Positioning modules

LD75P1, LD75P2


LD75P4



LD75D1, LD75D2


LD75D4


Flexible high-speed I/O control module
LD40PD01


High-speed counter module
LD62, LD62D


## CC-Link IE Field Network master/local module

LJ71GF11-T2


## CC-Link IE Field Network head module

LJ72GF15-T2


## CC-Link master/local module

LJ61BT11


## CC-Link/LT master module

LJ61CL12


## SSCNET III/H head module

LJ72MS15




## Ethernet interface module

## LJ71E71-100



## Serial communication modules

LJ71C24
LJ71C24-R2


## AnyWireASLINK master module

LJ51AW12AL DB


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- Support tools such as online e-learning courses, terminology dictionary, etc.
- Global sales and service network portal
- Latest news related to Mitsubishi Electric factory automation

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[^7]
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[^8]
## Product List

Please check the compatibility and restrictions of the product in the related manual before purchasing.
[ Legend ] DB : Double brand product ${ }^{(\text {Note) }}$ NEW : Recently released product SOON : Product available soon

MELSEC-L series

| Type | Model | Outline |
| :---: | :---: | :---: |
| CPU | L02SCPU | Number of I/O points: 1024 points, Number of I/O device points: 8192 points, Program capacity: 20K steps, Basic operation processing speed (LD instruction): 60 ns , Program memory capacity: 80 KB, Peripheral connection ports: USB and RS-232 (Predefined protocol support function), Memory card I/ F: None, Built-in I/O functions (General-purpose input: 16 points, General purpose output (Sink type): 8 points, Interrupt input, Pulse catch, Positioning, High-speed counter), END cover included |
|  | L02SCPU-P | Number of I/O points: 1024 points, Number of I/O device points: 8192 points, Program capacity: 20K steps, Basic operation processing speed (LD instruction): 60 ns , Program memory capacity: 80 KB , Peripheral connection ports: USB and RS-232 (Predefined protocol support function), Memory card I/F: None, Built-in I/O functions (General-purpose input: 16 points, General-purpose output (Source type): 8 points, Interrupt input, Pulse catch, Positioning, High-speed counter), END cover included |
|  | L02CPU | Number of I/O points: 1024 points, Number of I/O device points: 8192 points, Program capacity: 20K steps, Basic operation processing speed (LD instruction): 40 ns , Program memory capacity: 80 KB, Peripheral connection ports: USB and Ethernet (Predefined protocol support function), Memory card I/F: SD Memory Card, Built-in I/O functions (General-purpose input: 16 points, General-purpose output (Sink type): 8 points, Interrupt input, Pulse catch, Positioning, High-speed counter), END cover included |
|  | L02CPU-P | Number of I/O points: 1024 points, Number of I/O device points: 8192 points, Program capacity: 20K steps, Basic operation processing speed (LD instruction): 40 ns , Program memory capacity: 80 KB, Peripheral connection ports: USB and Ethernet (Predefined protocol support function), Memory card I/F: SD Memory Card, Built-in I/O functions (General-purpose input: 16 points, General-purpose output (Source type): 8 points, Interrupt input, Pulse catch, Positioning, High-speed counter), END cover included |
|  | L06CPU | Number of I/O points: 4096 points, Number of I/O device points: 8192 points, Program capacity: 60K steps, Basic operation processing speed (LD instruction): 9.5 ns , Program memory capacity: 240 KB, Peripheral connection ports: USB and Ethernet (Predefined protocol support function), Memory card I/F: SD Memory Card, Built-in I/O functions (General-purpose input: 16 points, General-purpose output (Sink type): 8 points, Interrupt input, Pulse catch, Positioning, High-speed counter), END cover included |
|  | L06CPU-P | Number of I/O points: 4096 points, Number of I/O device points: 8192 points, Program capacity: 60K steps, Basic operation processing speed (LD instruction): 9.5 ns, Program memory capacity: 240 KB, Peripheral connection ports: USB and Ethernet (Predefined protocol support function), Memory card I/F: SD Memory Card, Built-in I/O functions (General-purpose input: 16 points, General-purpose output (Source type): 8 points, Interrupt input, Pulse catch, Positioning, High-speed counter), END cover included |
|  | L26CPU | Number of I/O points: 4096 points, Number of I/O device points: 8192 points, Program capacity: 260K steps, Basic operation processing speed (LD instruction): 9.5 ns , Program memory capacity: 1040 KB, Peripheral connection ports: USB and Ethernet (Predefined protocol support function), Memory card I/F: SD Memory Card, Built-in I/O functions (General-purpose input: 16 points, General-purpose output (Sink type): 8 points, Interrupt input, Pulse catch, Positioning, High-speed counter), END cover included |
|  | L26CPU-P | Number of I/O points: 4096 points, Number of I/O device points: 8192 points, Program capacity: 260K steps, Basic operation processing speed (LD instruction): 9.5 ns , Program memory capacity: 1040 KB, Peripheral connection ports: USB and Ethernet (Predefined protocol support function), Memory card I/F: SD Memory Card, Built-in I/O functions (General-purpose input: 16 points, General-purpose output (Source type): 8 points, Interrupt input, Pulse catch, Positioning, High-speed counter), END cover included |
|  | L26CPU-BT | Number of I/O points: 4096 points, Number of I/O device points: 8192 points, Program capacity: 260K steps, Basic operation processing speed (LD instruction): 9.5 ns , Program memory capacity: 1040 KB, Peripheral connection ports: USB and Ethernet (Predefined protocol support function), Memory card I/F: SD Memory Card, Built-in I/O functions (General-purpose input: 16 points, General-purpose output (Sink type): 8 points, Interrupt input, Pulse catch, Positioning, High-speed counter), CC-Link master/local station function, END cover included |
|  | L26CPU-PBT | Number of I/O points: 4096 points, Number of I/O device points: 8192 points, Program capacity: 260K steps, Basic operation processing speed (LD instruction): 9.5 ns , Program memory capacity: 1040 KB, Peripheral connection ports: USB and Ethernet (Predefined protocol support function), Memory card I/F: SD Memory Card, Built-in I/O functions (General-purpose input: 16 points, General-purpose output (Source type): 8 points, Interrupt input, Pulse catch, Positioning, High-speed counter), CC-Link master/local station function, END cover included |
| CPU packages | L02CPU-SET | CPU module (L02CPU), Display unit (L6DSPU), and Power supply module (L61P) set |
|  | L02CPU-P-SET | CPU module (L02CPU-P), Display unit (L6DSPU), and Power supply module (L61P) set |
|  | L06CPU-SET | CPU module (L06CPU), Display unit (L6DSPU), and Power supply module (L61P) set |
|  | L06CPU-P-SET | CPU module (L06CPU-P), Display unit (L6DSPU), and Power supply module (L61P) set |
|  | L26CPU-SET | CPU module (L26CPU), Display unit (L6DSPU), and Power supply module (L61P) set |
|  | L26CPU-P-SET | CPU module (L26CPU-P), Display unit (L6DSPU), and Power supply module (L61P) set |
|  | L26CPU-BT-SET | CPU module (L26CPU-BT), Display unit (L6DSPU), and Power supply module (L61P) set |
|  | L26CPU-PBT-SET | CPU module (L26CPU-PBT), Display unit (L6DSPU), and Power supply module (L61P) set |

MELSEC-L series

| Type |  |  | Model | Outline |
| :---: | :---: | :---: | :---: | :---: |
| CPU options | Display unit |  | L6DSPU | STN black-and-white LCD, 16 characters x 4 lines |
|  | Battery |  | Q6BAT | Replacement battery |
|  |  |  | Q7BAT-SET | High capacity battery with a battery holder for CPU installation |
|  |  |  | Q7BAT | High capacity replacement battery |
|  | SD Memory Card |  | NZ1MEM-2GBSD*1 | SD memory card, capacity: 2 GB |
|  |  |  | NZ1MEM-4GBSD*1 | SDHC memory card, capacity: 4 GB |
|  |  |  | NZ1MEM-8GBSD*1 | SDHC memory card, capacity: 8 GB |
|  |  |  | NZ1MEM-16GBSD*1 | SDHC memory card, capacity: 16 GB |
|  | RS-232 adapter |  | L6ADP-R2 | For GOT(HMI) connection, $1 \times$ RS-232 channel, maximum transmission speed: 115.2Kpbs, MELSOFT connectable <br> MODBUS ${ }^{\oplus}$ RTU master function (using predefined protocol support function) |
|  | RS-422/485 adapter |  | L6ADP-R4 | For GOT(HMI) connection, $1 \times$ RS-422/485 channel, maximum transmission speed: 115.2Kpbs MODBUS ${ }^{\circledR}$ RTU master function (using predefined protocol support function) |
| END cover with error terminal |  |  | L6EC-ET | END cover with error terminal |
| Power supply |  |  | L61P | Input voltage: 100... 240 V AC, Output voltage: 5 V DC, Output current: 5 A |
|  |  |  | L63P | Input voltage: 24 V DC, Output voltage: 5 V DC, Output current: 5 A |
| Slim type Power supply |  |  | L63SP | Input voltage: 24 V DC, Output voltage: 5 V DC, Output current: 5 A , No isolation |
| Branch / Extension module |  |  | L6EXB | Branch module |
|  |  |  | L6EXE | Extension module with END cover |
|  | Extension cable |  | LC06E | $0.6-\mathrm{m}$ cable for connecting branch and extension modules |
|  |  |  | LC10E | $1.0-\mathrm{m}$ cable for connecting branch and extension modules |
|  |  |  | LC30E | 3.0-m cable for connecting branch and extension modules |
| I/O module | Input | AC input | LX10 | 16 points, 100... 120 V AC, Response time: 20 ms or less, 16 points/common, 18-point terminal block |
|  |  |  | LX28 | 8 points, 100... 240 V AC, Response time: 20 ms or less, 8 points/common, 18-point terminal block |
|  |  | DC input | LX40C6 | 16 points, 24 V DC, Response time: 1/5/10/20/70 ms or less, 16 points/common, Positive/Negative common, 18-point terminal block |
|  |  |  | LX41C4 | 32 points, 24 V DC, Response time: 1/5/10/20/70 ms or less, 32 points/common, Positive/Negative common, 40-pin connector |
|  |  |  | LX42C4 | 64 points, 24 V DC, Response time: 1/5/10/20/70 ms or less, 32 points/common, Positive/Negative common, 40-pin connector x2 |
|  | Relay |  | LY10R2 | 16 points, 24 V DC/240 V AC, $2 \mathrm{~A} /$ point, $8 \mathrm{~A} /$ common, Response time: 12 ms or less, 16 points/common, 18-point terminal block |
|  |  |  | LY18R2A | 8 points, 24 V DC/240 V AC, $2 \mathrm{~A} /$ point, $8 \mathrm{~A} /$ module, Response time: 12 ms or less, No common (all points independent), 18-point terminal block |
|  | Output | Triac | LY20S6 | 16 points, $100 \ldots .240 \mathrm{~V} \mathrm{AC}, 0.6 \mathrm{~A} /$ point, $4.8 \mathrm{~A} /$ common, Response time: $1 \mathrm{~ms}+0.5$ cycles or less, 16 points/common, 18-point terminal block |
|  |  |  | LY28S1A | 8 points, $100 \ldots 240 \mathrm{~V}$ DC, $1 \mathrm{~A} /$ point, $8 \mathrm{~A} /$ module, Response time: $1 \mathrm{~ms}+0.5$ cycles or less, No common (all points independent), 18-point terminal block |
|  |  | $\begin{aligned} & \text { Transistor } \\ & \text { (Sink) } \end{aligned}$ | LY40NT5P | 16 points, $12 \ldots 24 \mathrm{~V}$ DC, $0.5 \mathrm{~A} /$ point, $5 \mathrm{~A} /$ common, Response time: 1 ms or less, 16 points/common, 18-point terminal block, overload protection function, overheat protection function, surge suppression |
|  |  |  | LY41NT1P | 32 points, $12 \ldots 24$ V DC, $0.1 \mathrm{~A} /$ point, $2 \mathrm{~A} /$ common, Response time: 1 ms or less, 32 points/common, Sink type, 40-pin connector, overload protection function, overheat protection function, surge suppression |
|  |  |  | LY42NT1P | 64 points, $12 \ldots .24 \mathrm{~V}$ DC, $0.1 \mathrm{~A} /$ point, $2 \mathrm{~A} /$ common, Response time: 1 ms or less, 32 points/common, Sink type, 40-pin connector x2, overload protection function, overheat protection function, surge suppression |
|  |  | Transistor (Source) | LY40PT5P | 16 points, $12 \ldots .24 \mathrm{~V}$ DC, $0.5 \mathrm{~A} /$ point, $5 \mathrm{~A} /$ common, Response time: 1 ms or less, 16 points/common, 18-point terminal block, overload protection function, overheat protection function, surge suppression |
|  |  |  | LY41PT1P | 32 points, $12 \ldots 24 \mathrm{~V}$ DC, $0.1 \mathrm{~A} /$ point, $2 \mathrm{~A} /$ common, Response time: 1 ms or less, 32 points/common, 40-pin connector, overload protection function, overheat protection function, surge suppression |
|  |  |  | LY42PT1P | 64 points, $12 \ldots 24 \mathrm{~V}$ DC, $0.1 \mathrm{~A} /$ point, $2 \mathrm{~A} /$ common, Response time: 1 ms or less, 32 points/common, 40-pin connector x2, overload protection function, overheat protection function, surge suppression |
|  | I/O combined | DC input/transistor output (sink) | LH42C4NT1P | Input specifications$: 32$ points, $24 \mathrm{~V} \mathrm{DC} ,\mathrm{Response} \mathrm{time:} 1 / 5 / 10 / 20 / 70 \mathrm{~ms}$ or less,  <br>  32 points/common, Positive/Negative common  <br> Output specifications : 32 points, $12 \ldots 24 \mathrm{VDC}, 0.1 \mathrm{~A} /$ point, $2 \mathrm{~A} /$ common, Response time: 1 ms or less,  <br>  32 points/common, overload protection function, overheat protection function, <br> surge suppression <br> $40-$ pin connector x2  |
|  |  | DC input/transistor output (source) | LH42C4PT1P | Input specifications$: 32$ points, $24 \mathrm{~V} \mathrm{DC} ,\mathrm{Response} \mathrm{time:} 1 / 5 / 10 / 20 / 70 \mathrm{~ms}$ or less, <br> 32 points/common, Positive/Negative common  <br> Output specifications : 32 points, $12 \ldots 24 \mathrm{VDC}, 0.1 \mathrm{~A} /$ point, $2 \mathrm{~A} /$ common, Response time: 1 ms or less,  <br>  32 points/common, overload protection function, overheat protection function, <br> surge suppression <br> $40-$ pin connector x2  |
| Space module |  |  | LG69 | Space module for AnS module replacement |
| Spring clamp terminal block |  |  | L6TE-18S | Alternative to a 18-point screw terminal block, $0.3 \ldots 1.0 \mathrm{~mm}^{2}$ (AWG22...18), push-in type |

*1: Mitsubishi Electric does not guarantee the operation of non-Mitsubishi Electric products.

## MELSEC-L series

| Type |  | Model | Outline |
| :---: | :---: | :---: | :---: |
| Multiple input (voltage/current/temperature) modules |  | L60MD4-G | 4 channels, Input: -10... 10 V DC, $0 \ldots 20 \mathrm{mADC}$, <br> micro voltage-100... 100 mV DC, Thermocouple (K, J, T, E, N, R, S, B, U, L, PL II, W5Re/W26Re), <br> RTD (Pt1000, Pt100, JPt100, Pt50), Output (resolution): 0...20000, -20000...20000, (with voltage, current, micro voltage input) Conversion speed: $50 \mathrm{~ms} /$ channels, 18 -point terminal block, Channel isolated |
| Analog I/O module | Analog input | L60AD4 | 4 channels, Input: - $10 \ldots 10$ V DC, $0 \ldots 20 \mathrm{~mA}$ DC, Output (resolution): $0 . . .20000,-20000 \ldots 20000$, Conversion speed: $20 \mu \mathrm{~s}, 80 \mu \mathrm{~s}, 1 \mathrm{~ms} /$ channel, 18 -point terminal block |
|  |  | L60ADVL8 | 8 channels, Input: -10... 10 V , Output (resolution)-16000...16000, Conversion speed: $1 \mathrm{~ms} /$ channels 18-point terminal block |
|  |  | L60ADIL8 | 8 channels, Input: $0 \ldots . .20 \mathrm{~mA} \mathrm{DC}$, Output (resolution): $0 \ldots . .8000$, Conversion speed: $1 \mathrm{~ms} /$ channels 18-point terminal block |
|  |  | L60AD4-2GH | 4 channels, Input: -10... 10 V DC, $0 . . .20 \mathrm{~mA}$ DC, Output (resolution): $0 . . .32000,-32000 \ldots 32000$, Conversion speed: $40 \mu \mathrm{~s} / 2$ channels, 18 -point terminal block, Dual channel isolation |
|  | Analog output | L60DA4 | 4 channels, Input (resolution): $0 \ldots 20000,-20000 \ldots 20000$, Output: - $10 \ldots 10 \mathrm{~V}$ DC, $0 \ldots 20 \mathrm{mADC}$, Conversion speed: $20 \mu \mathrm{~s} /$ channel, 18 -point terminal block |
|  | Analog I/O | L60AD2DA2 |  |
| Temperature input module | RTD input | L60RD8 | 8 channels, RTD (Pt1000, Pt100, JPt100, Pt50, Ni500, Ni120, Ni100, Cu100, Cu50) Resolution: $0.1^{\circ} \mathrm{C}$, Conversion speed: $40 \mathrm{~ms} / \mathrm{ch}, 24$-point spring clamp terminal block |
| Temperature control module | Thermocouple input | L60TCTT4 | 4 channels (normal mode) /2 channels (heating-cooling control), Thermocouple (K, J, T, B, S, E, R, N, U, L, PL II, W5Re/W26Re), No Heater disconnection detection function, sampling cycle: $250 \mathrm{~ms} / 4$ channels, $500 \mathrm{~ms} / 4$ channels, Channel isolated, 18 point terminal block |
|  |  | L60TCTT4BW | 4 channels (normal mode)/2 channels (heating-cooling control), <br> Thermocouple (K, J, T, B, S, E, R, N, U, L, PL II, W5Re/W26Re), Heater disconnection detection function, Sampling cycle: $250 \mathrm{~ms} / 4$ channels, $500 \mathrm{~ms} / 4$ channels, Channel isolated, 18 point terminal block x2 |
|  | RTD input | L60TCRT4 | 4 channels (normal mode) /2 channels (heating-cooling control), <br> Platinum type resistive temperature device(Pt100, JPt100), No Heater disconnection detection function, Sampling cycle: $250 \mathrm{~ms} / 4$ channels, $500 \mathrm{~ms} / 4$ channels, Channel isolated, 18 point terminal block |
|  |  | L60TCRT4BW | 4 channels (normal mode) /2 channels (heating-cooling control), <br> Platinum type resistive temperature device (Pt100, JPt100), Heater disconnection detection function, Sampling cycle: $250 \mathrm{~ms} / 4$ channels, $500 \mathrm{~ms} / 4$ channels, Channel isolated, 18 point terminal block x2 |
| Simple motion module | SSCNET II/H | LD77MS2*1 | 2 axes, 2-axis linear interpolation, 2-axis circular interpolation, synchronous control, Control unit: mm, inch, degree, pulse, Number of positioning data: 600 data/axis, SSCNET III/H connectivity |
|  |  | LD77MS4*1 | 4 axes, 2-/3-/4-axis linear interpolation, 2-axis circular interpolation, synchronous control, Control unit: mm, inch, degree, pulse, Number of positioning data: 600 data/axis, SSCNET III/H connectivity |
|  |  | LD77MS16*1 | 16 axes, 2-/3-/4-axis linear interpolation, 2-axis circular interpolation, synchronous control, Control unit: mm, inch, degree, pulse, Number of positioning data: 600 data/axis, SSCNET III/H connectivity |
| Positioning module | Open collector | LD75P1 | 1 axis, Control unit: mm, inch, degree, pulse, <br> Number of positioning data: 600 data/axis, Maximum output pulse: 200 kpps , 40 -pin connector |
|  |  | LD75P2 | 2 axes, 2-axis linear interpolation, 2-axis circular interpolation, Control unit: mm , inch, degree, pulse, Number of positioning data: 600 data/axis, Maximum output pulse: $200 \mathrm{kpps}, 40$-pin connector |
|  |  | LD75P4 | 4 axes, 2-/3-/4-axis linear interpolation, 2-axis circular interpolation, Control unit: mm , inch, degree, pulse, Number of positioning data: 600 data/axis, Maximum output pulse: $200 \mathrm{kpps}, 40$-pin connector x2 |
|  | Differential driver | LD75D1 | 1 axis, Control unit: mm, inch, degree, pulse, Number of positioning data: 600 data/axis, Maximum output pulse: 4 Mpps, 40-pin connector |
|  |  | LD75D2 | 2 axes, 2-axis linear interpolation, 2-axis circular interpolation, Control unit: mm , inch, degree, pulse, Number of positioning data: 600 data/axis, Maximum output pulse: 4 Mpps, 40 -pin connector |
|  |  | LD75D4 | 4 axes, 2-/3-/4-axis linear interpolation, 2-axis circular interpolation, Control unit: mm , inch, degree, pulse, Number of positioning data: 600 data/axis, Maximum output pulse: 4 Mpps, 40 -pin connector $\times 2$ |
| Flexible high-speed I/O control module |  | LD40PD01 | 12 input points (all for 5 V DC/24 V DC/differential) <br> 14 output points ( 8 points for DC ( 5 V DC... 24 V ), 6 points for differential) |
| High-speed counter module |  | LD62 | 2 channels, 200/100/10 kpps, Count input signal: 5/12/24 V DC, External input: $5 / 12 / 24 \mathrm{~V}$ DC, Coincidence output: transistor (sink), $12 / 24 \mathrm{~V} \mathrm{DC}, 0.5 \mathrm{~A} /$ point, $2 \mathrm{~A} /$ common, 40 -pin connector |
|  |  | LD62D | 2 channels, $500 / 200 / 100 / 10 \mathrm{kpps}$, Count input signal: EIA standards RS-422-A (Differential line driver level), External input: $5 / 12 / 24 \mathrm{~V}$ DC, Coincidence output: transistor (sink), $12 / 24 \mathrm{~V} \mathrm{DC}, 0.5 \mathrm{~A} /$ point, $2 \mathrm{~A} /$ common, 40-pin connector |

*1: The connector is not appended. Please obtain an LD77MHIOCON separately.

MELSEC-L series

| Type |  | Model | Outline |
| :---: | :---: | :---: | :---: |
| Network module | CC-Link IE Field Network | LJ71GF11-T2 | Master/Local station |
|  |  | LJ72GF15-T2*1 | Remote station (Head module with END cover) |
|  | CC-Link | LJ61BT11 | Master/Local station, CC-Link Ver.2.0 compatible |
|  | CC-Link/LT | LJ61CL12 | Master station, CC-Link/LT system compatible |
|  | SSCNET III/H | LJ72MS15*2 | Remote station (Head module with END cover) |
|  | Ethernet interface | LJ71E71-100 | 10BASE-T/100BASE-TX <br> BACnet ${ }^{\text {TM }}$ client function, MODBUS ${ }^{\circledR}$ TCP master function (using predefined protocol support function) |
|  | Serial communication | LJ71C24 | RS-232: 1 channel, RS-422/485: 1 channel, Total transmission speed of 2 channels: 230.4 kbps MODBUS ${ }^{\circledR}$ RTU master function (using predefined protocol support function) |
|  |  | LJ71C24-R2 | RS-232: 2 channels, Total transmission speed of 2 channels: 230.4 kbps MODBUS® RTU master function (using predefined protocol support function) |
| Digital link sensor |  | LJ51AW12AL DB | AnyWireASLINK system compatible master module |

*1: The CPU module, branch and extension module, display unit, RS-232 adapter, CC-Link IE Field Network master/local module and Ethernet interface module cannot be mounted on a system using LJ72GF-T2.
*2: The CPU module, branch and extension module, display unit, RS-232 adapter, temperature control module, simple motion module, positioning module, CC-Link IE Field Network master/local module, CC-Link IE Field network head module, CC-Link master/local module, CC-Link/LT master module, Ethernet interface module, serial communication module, and AnyWireASLINK master module cannot be mounted on a system using LJ72MS15.

Compatible module for each protocol

| Compatible protocol | Compatible module | Model | Outline |
| :---: | :---: | :---: | :---: |
| SLMP <br> (MC protocol) | CPU (Built-in Ethernet) | $\begin{array}{\|l\|} \hline \text { L02CPU(-P) } \\ \text { L06CPU(-P) } \\ \text { L26CPU(-P) } \\ \text { L26CPU-(P)BT } \\ \hline \end{array}$ | SLMP server function (only MC protocol QnA compatible 3E frame) SLMP client function (using predefined protocol support function) |
|  | Ethernet interface module | LJ71E71-100 | SLMP server function (including MC protocol) <br> SLMP client function (using predefined protocol support function) |
| BACnet ${ }^{\text {TM }}$ | CPU (Built-in Ethernet) | $\begin{aligned} & \hline \text { L02CPU(-P) } \\ & \text { L06CPU(-P) } \\ & \text { L26CPU(-P) } \\ & \text { L26CPU-(P)BT } \\ & \hline \end{aligned}$ | Compatible BACnet ${ }^{\text {TM }}$ object: Analog Input (AI), Binary Input (BI), Binary Output (BO), Accumulator (AC) <br> (using predefined protocol support function) |
|  | Ethernet interface module | LJ71E71-100 |  |
| MODBUS®/TCP | CPU (Built-in Ethernet) | $\begin{aligned} & \hline \text { L02CPU(-P) } \\ & \text { L06CPU(-P) } \\ & \text { L26CPU(-P) } \\ & \text { L26CPU-(P)BT } \\ & \hline \end{aligned}$ | MODBUS ${ }^{\circledR} / T C P$ communication master function (using predefined protocol support function) |
|  | Ethernet interface module | LJ71E71-100 |  |
| MODBUS ${ }^{\text {® }}$ | CPU (Built-in RS-232) | L02SCPU(-P) | MODBUS®RTU communication master function (using predefined protocol support function) |
|  | RS-232 adapter | L6ADP-R2 |  |
|  | RS-422/485 adapter | L6ADP-R4 |  |
|  | Serial Communication Modules | LJ71C24(-R2) |  |

## Options

| Type | Model | Outline |
| :---: | :---: | :---: |
| Connector | A6CON1*3*4 | Soldering type 32-point connector (40-pin connector) |
|  | A6CON2*3*4 | Crimp contact type 32-point connector (40-pin connector) |
|  | A6CON3 ${ }^{* 3 * 5}$ | Flat cable pressure welding type 32-point connector (40-pin connector) |
|  | A6CON4*3*4 | Soldering type 32-point connector (40-pin connector, cable connectable in bidirection) |
| Connector/terminal block converter module | A6TBXY36*6*7*8 | For positive common type input module and sink type output module (Standard type) |
|  | A6TBXY54*6*7*8 | For positive common type input module and sink type output module (2-wire type) |
|  | A6TBX70*6*9 | For positive common type input module (3-wire type) |

*3: Available for the L Series CPU, LX41C4, LX42C4, LY41NT1P, LY42NT1P, LY41PT1P, LY42PT1P, LH42C4NT1P, and LH42C4PT1P.
*4: Available for LD75P1, LD75P2, LD75P4, LD75D1, LD75D2, LD75D4, LD40PD01, LD62 and LD62D.
${ }^{*} 5$ : Available for the L Series CPU when using all the I/O signals for normal I/O output functions.
*6: Available for LX41C4 and LX42C4. (Positive common only)
*7: Available for LY41NT1P, LY42NT1P, LY41PT1P and LY42PT1P.
*8: Available for LH42C4NT1P and LH42C4PT1P. (Input side only when using plus common.)
*9: Available for LH42C4NT1P and LH42C4PT1P. (Input side only when using plus common. Output side is not usable.)

## Ethernet related products

| Type |  | Model | Outline |
| :---: | :---: | :---: | :---: |
| Wireless LAN Adapter | U.S.A. | NZ2WL-US*10*11 DB | Conforms to IEEE 802.11a, IEEE 802.11b, IEEE 802.11g standards |
|  | Europe | NZ2WL-EU*10*11 DB | Conforms to IEEE 802.11a, IEEE 802.11b, IEEE 802.11g standards |
|  | China | NZ2WL-CN**10*11 DB | Conforms to IEEE 802.11a, IEEE 802.11b, IEEE 802.11g standards |
|  | Korea | NZ2WL-KR*10*11 DB | Conforms to IEEE 802.11a, IEEE 802.11b, IEEE 802.11g standards |
|  | Taiwan | NZ2WL-TW**10*11 DB | Conforms to IEEE 802.11a, IEEE 802.11b, IEEE 802.11g standards |
| Industrial switching HUB |  |  | $10 \mathrm{Mbps} / 100 \mathrm{Mbps} / 1$ Gbps AUTO-MDIX, DIN rail mountable, 8 ports |
|  |  | NZ2EHF-T8 DB | $10 \mathrm{Mbps} / 100 \mathrm{Mbps}$ AUTO-MDIX, DIN rail mountable, 8 ports |

[^9]*11: Both access points and stations are supported, and can be switched with the settings.
"For details on the software versions compatible with each module, refer to the manual for each product.
Please contact your local Mitsubishi Electric sales office or representative for the latest information about MELSOFT software versions and compatible operating systems.

MELSOFT — Programming Tool

| Type | Model | Outline |
| :---: | :---: | :---: |
| MELSOFT iQ Works | SW2DND-IQWK-E | FA engineering software ${ }^{\star 1}$ <br> - System Management Software: MELSOFT Navigator <br> - Controller Programming Software: MELSOFT GX Works3*2, GX Works2, GX Developer <br> - Motion Programming Software: MELSOFT MT Works2 <br> - HMI Programming Software: MELSOFT GT Works3 <br> - Robot Programing Software: MELSOFT RT ToolBox2 mini <br> - Inverter Setup Software: MELSOFT FR Configurator2 <br> - C Controller setting and monitoring tool: MELSOFT CW Configurator <br> - MITSUBISHI ELECTRIC FA Library |
| MELSOFT GX Works3 | SW1DND-GXW3-E | Controller Programming Software: MELSOFT GX Works3*2 MITSUBISHI ELECTRIC FA Library Comes with GX Works2 and GX Developer |
| MELSOFT GX Works2 | SW1DNC-GXW2-E | Controller Programming Software Comes with GX Developer |
| MELSOFT MX Component | SW4DNC-ACT-E | Active ${ }^{\ominus}$ library for communication |
|  | SW1DNC-ACTAND-B | Library for communication (for Android application development) (Japanese/English version) |
|  | SW1MIC-ACTIOS-B | Library for communication (for iOS application development) (Japanese/English version) |
| MELSOFT MX Sheet | SW2DNC-SHEET-E*3 | Excel ${ }^{\oplus}$ communication support tool |
| MELSOFT MX Works | SW2DNC-SHEETSET-E | A set of two products: MELSOFT MX Component, MELSOFT MX Sheet |

*1: For detailed information about supported modules, refer to the manuals of the relevant software package.
*2: The MELSOFT GX Works3 menu is switchable between Japanese, English, and simplified Chinese. (Traditional Chinese and Korean will be supported soon.)
*3: To use MELSOFT MX Sheet, MELSOFT MX Component is required.

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[^0]:    *1: Option (sold separately). Does not support LO2SCPU(-P).
    *2: Included with L26CPU-(P)BT
    *3: Included with L02CPU(-P), L06CPU(-P), L26CPU(-P), L26CPU-(P)BT

[^1]:    When adding a branch module to a fully occupied block, relocate one of the
    other modules to a new block to give way to the branch module.

[^2]:    *1: There is no isolation between the primary side 24 V DC and secondary side 5 V DC

[^3]:    *3: Only temperature measurement using a temperature input terminal can be performed.
    *4: Heating-cooling control is performed using an output module in the system.

[^4]:    *2: For further information on "Flexible High-Speed I/O Control Module Configuration Tool", please contact your local Mitsubishi sales representative

[^5]:    *1: The total number of modules that can be installed onto a CC-Link IE Field Network head module. (END cover and power supply module are not included.) Note that only one head module per system is possible.
    *2: Standard (straight type) cable.

[^6]:    *2: When the cables other than dedicated flat cables, VCTF cables, and flexible cables are used, performance of CCLink/LT is not guaranteed
    ${ }^{*} 3$ : Use the dedicated flat cables and flexible cables accredited by CC-Link Partner Association. CC-Link Partner Association website: http://www.cc-link.org
    *4: Refer to the manual for details regarding VCTF cable specifications.
    *5: Set the number of occupied I/O points using the operation setting switch. Refer to the manual for details.
    *6: 24 V DC power supply is supplied through the dedicated power supply or power supply adapter.

[^7]:    ■ Beginner level
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[^8]:    *1: When using a tablet not listed above, 7 -inch (resolution of $1920 \times 1200$ dots (WUXGA)) or better is recommended.

[^9]:    *10: Each product is usable only in the respective country.

